

# ON ADDITIVE SOLUTIONS OF A LINEAR EQUATION

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ABSTRACT. In this paper we investigate the functional equation

$$\sum_{i=1}^n \alpha_i A(\beta_i x) = 0$$

which holds for all  $x \in \mathbb{R}$  with an unknown additive function  $A: \mathbb{R} \rightarrow \mathbb{R}$  and fixed real parameters  $\alpha_i, \beta_i$ , where  $i = 1, \dots, n$ . Here we give sufficient and necessary conditions for the existence of non-trivial additive solutions of equation above in some cases depending on the algebraic properties of the parameters.

## 1. INTRODUCTION AND PRELIMINARIES

Consider the functional equation

$$(1.1) \quad \sum_{i=1}^n \alpha_i A(\beta_i x) = 0$$

which holds for all  $x \in \mathbb{R}$  (the reals) with an unknown additive function  $A: \mathbb{R} \rightarrow \mathbb{R}$  and fixed real parameters  $\alpha_i, \beta_i$ , where  $i = 1, \dots, n$ . Since for any additive function vanishes at  $x = 0$ , without loss of generality we can suppose that none of the parameters equals to zero.

The theory of functional equations containing weighted arithmetic means gives motivations to investigate (1.1) (see [4]).

(1.1) has been investigated for the case  $n = 2$  by Daróczy [2]. His fundamental result states that the functional equation

$$(1.2) \quad \alpha_1 A(\beta_1 x) + \alpha_2 A(\beta_2 x) = 0$$

has a non-trivial additive solution  $A$  if and only if both the parameters

$$\alpha := -\frac{\alpha_2}{\alpha_1} \quad \text{and} \quad \beta := \frac{\beta_1}{\beta_2}$$

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are transcendent or they are algebraic with the same defining polynomial over  $\mathbb{Q}$  (the rationals). Equation (1.2) is equivalent to

$$A(\beta x) = \alpha A(x) \quad (x \in \mathbb{R}),$$

i.e. the solutions must be semi-homogeneous. This is a motivation to find conditions for the existence of non-trivial semi-homogeneous solutions of equation (1.1) for the case  $n \geq 3$ . It is easy to see that equation (1.1) is equivalent to the equation

$$\sum_{i=1}^n \frac{\alpha_i}{\alpha_n} A\left(\frac{\beta_i}{\beta_n} x\right) = 0 \quad (x \in \mathbb{R}).$$

In terms of the parameters  $\frac{\alpha_1}{\alpha_n}, \dots, \frac{\alpha_{n-1}}{\alpha_n}$  and  $\frac{\beta_1}{\beta_n}, \dots, \frac{\beta_{n-1}}{\beta_n}$  ( $n \geq 3$ ) sufficient conditions can be found for the existence of non-trivial semi-homogeneous additive solutions in [3]. In connection with these results we need the following notions.

**Definition 1.1.** Let  $m$  be a positive integer and consider the element  $\vec{\lambda} := (\lambda_1, \dots, \lambda_m)$  of the coordinate space  $\mathbb{R}^m$ . If the ideal

$$\mathcal{I}(\vec{\lambda}) := \{ p \in \mathbb{Q}[x_1, \dots, x_m] \mid p(\lambda_1, \dots, \lambda_m) = 0 \}$$

of the polynomial ring  $\mathbb{Q}[x_1, \dots, x_m]$  contains only the zero polynomial we say that the coordinates  $\lambda_1, \dots, \lambda_m$  are algebraically independent. Otherwise they are algebraically dependent.

**Theorem 1.2.** *Suppose that  $n \geq 3$ . If the parameters  $\frac{\beta_1}{\beta_n}, \dots, \frac{\beta_{n-1}}{\beta_n}$  are algebraically independent and at least one of the parameters  $\frac{\alpha_1}{\alpha_n}, \dots, \frac{\alpha_{n-1}}{\alpha_n}$  is transcendent then equation (1.1) has non-trivial additive solutions which are semi-homogeneous in the sense that*

$$A\left(\frac{\beta_i}{\beta_n} x\right) = \delta_i A(x)$$

for some  $\delta_i$ 's, for all  $x \in \mathbb{R}$  and  $i = 1, \dots, n-1$ .

**Theorem 1.3.** *Suppose that  $n \geq 3$ . If the parameters  $\frac{\alpha_1}{\alpha_n}, \dots, \frac{\alpha_{n-1}}{\alpha_n}$  are algebraically independent and at least one of the parameters  $\frac{\beta_1}{\beta_n}, \dots, \frac{\beta_{n-1}}{\beta_n}$  is transcendent then equation (1.1) has non-trivial additive solution which is semi-homogeneous in the sense that*

$$A(\delta_i x) = \frac{\alpha_i}{\alpha_n} A(x)$$

for some  $\delta_i$ 's, for all  $x \in \mathbb{R}$  and  $i = 1, \dots, n-1$ .

For example the coordinates of  $(\sqrt{\pi}, 2\pi + 1)$  are algebraically dependent over  $\mathbb{Q}$ , since the non-zero polynomial  $P(x_1, x_2) = 2x_1^2 - x_2 + 1$  vanishes at  $(\sqrt{\pi}, 2\pi + 1)$ .

The Lindemann-Weierstrass theorem gives a method to construct algebraically independent systems (see [1], Theorem 1.4. p.6.). It says that if  $\lambda_1, \dots, \lambda_n$  are algebraic numbers such that they are linearly independent over  $\mathbb{Q}$ , then

$$e^{\lambda_1}, \dots, e^{\lambda_n}$$

are algebraically independent over  $\mathbb{Q}$ .

In this paper we give sufficient and necessary conditions for the existence of non-trivial additive solutions of (1.1) under some conditions like in Theorem 1.1 and Theorem 1.2.

## 2. GAUSS ELIMINATION PROCESS FOR A SYSTEM OF EQUATIONS CONTAINING AN UNKNOWN ADDITIVE FUNCTION

The main tool of our investigations is the following

**Theorem 2.1.** *Let  $k$  be a natural number such that  $k \geq 2$ . Furthermore, let  $u, a_{ij}$  be fixed real numbers ( $i, j = 1, \dots, k$ ). If the matrix  $M_1 := (a_{ij})_{k \times k}$  is regular, then the only additive function  $A: \mathbb{R} \rightarrow \mathbb{R}$  that satisfies the system of equations*

$$(2.1) \quad u^{k-1}A(a_{i1}x) + u^{k-2}A(a_{i2}x) + \dots + uA(a_{ik-1}x) + A(a_{ik}x) = 0$$

( $x \in \mathbb{R}; i = 1, \dots, k$ ) is the identically zero function.

*Proof.* For the simplicity  $M_1$  will be called the matrix of the system (2.1), and the equation

$$u^{k-1}A(\mu a_{i1}x) + u^{k-2}A(\mu a_{i2}x) + \dots + uA(\mu a_{ik-1}x) + A(\mu a_{ik}x) = 0$$

will be denoted by  $E_{i(\mu x)}^{k-1}$  for any indices  $i = 1, \dots, k$  and  $\mu \in \mathbb{R}$ .

In the proof we imitate the steps of the Gauss elimination process. Without loss of generality we may assume that  $a_{11} \neq 0$  because the rank of  $M_1$  is maximal. Taking the difference  $E_{i(a_{11}x)}^{k-1} - E_{1(a_{11}x)}^{k-1}$  ( $i = 2, \dots, k$ ) and using the additivity of  $A$  we get that

$$(2.2) \quad u^{k-2}A((a_{11}a_{i2} - a_{12}a_{i1})x) + \dots + uA((a_{11}a_{ik-1} - a_{1k-1}a_{i1})x) + \\ + A((a_{11}a_{ik} - a_{1k}a_{i1})x) = 0$$

holds for all  $x \in \mathbb{R}$  and for all indices  $i = 2, \dots, k$ . Equations (2.2) and  $E_{1(x)}^{k-1}$  form a system of equations which has the matrix

$$M_2 = \begin{pmatrix} a_{11} & a_{12} & \cdot & \cdot & a_{1k} \\ 0 & a_{11}a_{22} - a_{12}a_{21} & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & a_{11}a_{k2} - a_{12}a_{k1} & \cdot & \cdot & a_{11}a_{kk} - a_{1k}a_{k1} \end{pmatrix}.$$

We may suppose that  $a_{11}a_{22} - a_{12}a_{21} \neq 0$  because of the regularity of  $M_1$ . Continuing this process, in the  $(k-1)^{st}$  step the matrix  $M_1$  becomes of triangular form  $M_k := (\lambda_{ij})_{k \times k}$  for some  $\lambda_{ij} \in \mathbb{R}$  with  $\lambda_{ij} = 0$  if  $i > j$ . Since  $0 \neq \det M_1 = \det M_k = \prod_{i=1}^k \lambda_{ii}$  and the last equation of the system obtained in the  $(k-1)^{st}$  step is  $A(\lambda_{kk}x) = 0$  for all  $x \in \mathbb{R}$  we get that  $A$  is the identically zero function.  $\square$

### 3. THE MAIN RESULT

The new part of the main result of this paper is the following

**Theorem 3.1.** *Suppose that  $n \geq 3$ . If the parameters  $\frac{\beta_1}{\beta_n}, \dots, \frac{\beta_{n-1}}{\beta_n}$  are algebraically independent and all of the parameters  $\frac{\alpha_1}{\alpha_n}, \dots, \frac{\alpha_{n-1}}{\alpha_n}$  are algebraic then the only additive solution of equation (1.1) is the identically zero function.*

*Proof.* For the simplicity we use the notations

$$\omega_i := \frac{\alpha_i}{\alpha_n}, \quad \xi_i := \frac{\beta_i}{\beta_n} \quad (i = 1, \dots, n-1).$$

As  $\omega_i$  ( $i = 1, \dots, n-1$ ) is algebraic over  $\mathbb{Q}$ , therefore  $\mathbb{Q}(\omega_1, \dots, \omega_{n-1})$  is a finite extension of  $\mathbb{Q}$ . Moreover  $\mathbb{Q}$  is a field with zero characteristic, thus there exist  $u \in \mathbb{R}$  such that  $\mathbb{Q}(u) = \mathbb{Q}(\omega_1, \dots, \omega_{n-1})$ . Let  $k$  be the degree of extension. As  $1, u, \dots, u^{k-1}$  is a basis of the vector space  $\mathbb{Q}(u)$ , thus  $\omega_i = \sum_{j=0}^{k-1} r_{ij}u^j$  with some  $r_{ij} \in \mathbb{Q}$  ( $i = 1, \dots, n-1$ ;  $j = 0, \dots, k-1$ ). Using this form of  $\omega_i$ , equation (1.1) goes over into the equation

$$(3.1) \quad u^{k-1}A(p_{k-1}x) + u^{k-2}A(p_{k-2}x) + \dots + uA(p_1x) + A(p_0x) = 0$$

where  $p_j = \sum_{i=1}^{n-1} \xi_i r_{ij}$  ( $j = 1, \dots, k-1$ ) and  $p_0 = 1 + \sum_{i=1}^{n-1} \xi_i r_{i0}$ . It is easy to see that  $p_0 \neq 0$ . (Otherwise  $\xi_1, \dots, \xi_{n-1}$  can not be algebraically independent.) Let

$$f(t) := t^k + q_{k-1}t^{k-1} + \dots + q_1t + q_0 \quad (q_i \in \mathbb{Q}, \quad i = 0, \dots, k-1)$$

be the defining polynomial of  $u$ . Then we have that

$$(3.2) \quad u^k = -(q_{k-1}u^{k-1} + \dots + q_1u + q_0).$$

Multiplying both sides of (3.1) by  $u$  and using (3.2), the additivity and rational homogeneity of  $A$  we get that

$$(3.3) \quad u^{k-1}A((p_{k-2} - q_{k-1}p_{k-1})x) + \dots + u^2A((p_1 - q_2p_{k-1})x) + \\ + uA((p_0 - q_1p_{k-1})x) + A(-q_0p_{k-1}x) = 0.$$

Multiplying both sides of (3.3) by  $u$  and using the process above  $k-1$  times we get a system of equations of type (2.1). So, in what follows, it is enough to prove that the matrix  $M := (b_{ij})_{k \times k}$  of this system is regular, since by Theorem (2.1),  $A = 0$ .

Suppose, in contrary, that  $\det M = 0$ . One can easily check that  $b_{ij} = z^{(ij)}(\xi_1, \dots, \xi_{n-1})$  for some  $z^{(ij)} \in \mathbb{Q}[x_1, \dots, x_{n-1}]$  ( $i, j = 1, \dots, k$ ) therefore

$$\det M = z(\xi_1, \dots, \xi_{n-1})$$

where  $z \in \mathbb{Q}[x_1, \dots, x_{n-1}]$  is defined by

$$z(x_1, \dots, x_{n-1}) = \\ = \det \begin{pmatrix} z^{(11)}(x_1, \dots, x_{n-1}) & \dots & \dots & \dots & z^{(1k)}(x_1, \dots, x_{n-1}) \\ \vdots & & z^{(i \ k-i+1)}(x_1, \dots, x_{n-1}) & & \vdots \\ \vdots & & \vdots & & \vdots \\ z^{(k1)}(x_1, \dots, x_{n-1}) & \dots & \dots & \dots & z^{(kk)}(x_1, \dots, x_{n-1}) \end{pmatrix}.$$

We show that  $z$  is not the identically zero polynomial which contradicts to the algebraic independence of  $\xi_1, \dots, \xi_{n-1}$ .

To see this we show that  $z^{(ij)}$  does not vanish at the zero vector if  $j = k - i + 1$  ( $i = 1, \dots, k$ ), moreover in this case  $z^{(ij)}(0, \dots, 0) = 1$ , otherwise it vanishes. The proof of this statement goes by induction on  $i$ . If  $i = 1$  then the statement is true, because

$$z^{(1j)}(x_1, \dots, x_{n-1}) = \sum_{i=1}^{n-1} r_{ij}x_i \text{ thus } z^{(1j)}(0, \dots, 0) = 0 \quad (j = 1, \dots, k-1),$$

$$z^{(1k)}(x_1, \dots, x_{n-1}) = 1 + \sum_{i=1}^{n-1} r_{i0}x_i \text{ thus } z^{(1k)}(0, \dots, 0) = 1.$$

Assume that, for  $2 \leq i \leq k-1$ ,

$$z^{(1j)}(0, \dots, 0) = 0 \text{ if } j \neq k-i+1 \quad (j = 1, \dots, k) \text{ and } z^{(i \ k-i+1)}(0, \dots, 0) = 1$$

hold. Now we look for connection between the coefficients  $b_{i+1 \ j}$  and  $b_{il}$  ( $j, l = 1, \dots, k$ ).

Since the  $i^{\text{th}}$  equation of the system is

$$u^{k-1}A(b_{i1}x) + \dots + u^{i-1}A(b_{i \ k-i+1}x) + \dots + A(b_{ik}x) = 0$$

while the  $(i + 1)^{st}$  one is

$$-(q_{k-1}u^{k-1} + \dots + q_i u^i + \dots + q_0)A(b_{i1}x) + \dots + u^i A(b_{i, k-i+1}x) + \dots + uA(b_{ik}x) = 0,$$

that is,

$$u^{k-1}A((b_{i2} - q_{k-1}b_{i1})x) + \dots + u^i A((b_{i, k-i+1} - q_i b_{i1})x) + \dots + A(q_0 b_{i1}x) = 0,$$

we get that  $b_{i+1, j} = b_{i, j+1} - q_{k-j}b_{i1}$  ( $j = 1, \dots, k$ ). So, we have that  $z^{(i+1, j)} = z^{(i, j+1)} - q_{k-j}z^{(i1)}$  ( $j = 1, \dots, k$ ).

If  $j = k - i$  then  $z^{(i+1, k-i)} = z^{(i, k-i+1)} - q_i z^{(i1)}$ . Since  $z^{(i1)}(0, \dots, 0) = 0$  and  $z^{(i, k-i+1)}(0, \dots, 0) = 1$  it follows that  $z^{(i+1, k-i)}(0, \dots, 0) = 1$ .

If  $j \neq k - i$  then  $z^{(i, j+1)}(0, \dots, 0) = 0$  thus  $z^{(i+1, j)}(0, \dots, 0) = 0$ .

According to the facts above it follows that

$$z(0, \dots, 0) = \det \begin{pmatrix} 0 & \cdot & \cdot & \cdot & 0 & 1 \\ \cdot & & & & 1 & 0 \\ \cdot & & \cdot & & \cdot & \\ \cdot & & \cdot & & \cdot & \\ 0 & 1 & & & \cdot & \\ 1 & 0 & \cdot & \cdot & \cdot & 0 \end{pmatrix} = (-1)^{\frac{k(k+3)}{2}}$$

which implies that  $z$  is not the identically zero polynomial.  $\square$

The following theorem says that the role of the inner and outer parameters can be interchanged in Theorem 3.1.

**Theorem 3.2.** *Suppose that  $n \geq 3$ . If the parameters  $\frac{\alpha_1}{\alpha_n}, \dots, \frac{\alpha_{n-1}}{\alpha_n}$  are algebraically independent and all of the parameters  $\frac{\beta_1}{\beta_n}, \dots, \frac{\beta_{n-1}}{\beta_n}$  are algebraic then the only additive solution of equation (1.1) is the identically zero function.*

*Proof.* The proof is similar to that of the previous theorem. With the notations  $\omega_i := \frac{\alpha_i}{\alpha_n}$ ,  $\xi_i := \frac{\beta_i}{\beta_n}$  ( $i = 1, \dots, n-1$ ) we get that there exists  $u \in \mathbb{R}$  such that  $\mathbb{Q}(u) = \mathbb{Q}(\xi_1, \dots, \xi_{n-1})$ . If the degree of the extension is equal to  $k$  then  $1, u, \dots, u^{k-1}$  is a basis of  $\mathbb{Q}(u)$ , thus  $\xi_i = \sum_{j=0}^{k-1} r_{ij} u^j$  with some  $r_{ij} \in \mathbb{Q}$  ( $i = 1, \dots, n-1$ ;  $j = 0, \dots, k-1$ ). Using this form of  $\xi_i$  equation (1.1) goes over into the equation

$$(3.4) \quad p_{k-1}A(u^{k-1}x) + p_{k-2}A(u^{k-2}x) + \dots + p_1A(ux) + p_0A(x) = 0$$

where  $p_j = \sum_{i=1}^{n-1} \omega_i r_{ij}$  ( $j = 1, \dots, k-1$ ) and  $p_0 = 1 + \sum_{i=1}^{n-1} \omega_i r_{i0}$ . It is easy to see, that  $p_0 \neq 0$ . Using again the notation

$$f(t) := t^k + q_{k-1}t^{k-1} + \dots + q_1 t + q_0 \quad (q_i \in \mathbb{Q}, \quad i = 0, \dots, k-1)$$

for the defining polynomial of  $u$  we can use again the equality (3.2). Replace  $x$  by  $ux$  in (3.4). Using (3.2), the additivity and rational

homogeneity of  $A$  we get that

$$(3.5) \quad (p_{k-2} - q_{k-1}p_{k-1})A(u^{k-1}x) + \dots + (p_1 - q_2p_{k-1})A(u^2x) + \\ + (p_0 - q_1p_{k-1})A(ux) + (-q_0p_{k-1})A(x) = 0.$$

Replace  $x$  by  $u^2x, \dots, u^{k-1}x$ , respectively in equation (3.4). Then we get a system of equations with  $k$  unknowns and  $k$  equations which has the matrix form

$$L \begin{pmatrix} A(u^{k-1}x) \\ \vdots \\ A(ux) \\ A(x) \end{pmatrix} = 0$$

where  $L := (c_{ij})_{k \times k}$  consists of the coefficients of the system. We are going to prove that  $\det L \neq 0$  which means that the linear transformation represented by  $L$  is regular and the kernel contains only the zero vector. Hence  $A(x) = 0$  for any  $x \in \mathbb{R}$ .

Suppose, in contrary that  $\det L = 0$ . It is easy to see that

$$c_{ij} = z^{(ij)}(\omega_1, \dots, \omega_{n-1}) \text{ for some } z^{(ij)} \in \mathbb{Q}[x_1, \dots, x_{n-1}] \quad (i, j = 1, \dots, k).$$

Therefore  $\det L = z(\omega_1, \dots, \omega_{n-1})$  where  $z \in \mathbb{Q}[x_1, \dots, x_{n-1}]$  is defined as in the proof of Theorem 3.1. Like in the proof of Theorem 3.1, we can show that

$$(3.6) \quad z^{(ij)}(0, \dots, 0) = 0 \text{ if } j \neq k - i + 1 \quad (i, j = 1, \dots, k) \text{ and } z^{(i \ k-i+1)}(0, \dots, 0) = 1,$$

which implies that  $z(0, \dots, 0) = (-1)^{\frac{k(k+3)}{2}}$ . This means that  $z$  is not the identically zero polynomial which contradicts to the algebraic independence of  $\omega_1, \dots, \omega_{n-1}$ . (3.6) can be proved by induction on  $i$  using the connection of coefficients  $c_{i+1 \ j}$  and  $c_{i \ l}$ . As it was in the proof of Theorem 3.1 this connection can easily be found if we consider the  $i^{\text{th}}$  equation

$$c_{i1}A(u^{k-1}x) + \dots + c_{i \ k-i+1}A(u^{i-1}x) + \dots + c_{ik}A(x) = 0$$

and the  $(i+1)^{\text{st}}$  one

$$(c_{i2} - q_{k-1}c_{i1})A(u^{k-1}x) + \dots + (c_{i \ k-i+1} - q_i c_{i1})A(u^i x) + \dots + q_0 c_{i1}A(x) = 0$$

from the system of equations.  $\square$

Combining Theorems 1.1 and 3.1, Theorems 1.2 and 3.2, respectively we have the following main results.

**Theorem 3.3.** *Suppose that  $n \geq 3$  and the parameters  $\frac{\beta_1}{\beta_n}, \dots, \frac{\beta_{n-1}}{\beta_n}$  are algebraically independent. There exist a not identically zero additive solution of equation (1.1) if and only if at least one of the parameters  $\frac{\alpha_1}{\alpha_n}, \dots, \frac{\alpha_{n-1}}{\alpha_n}$  is transcendent.*

**Theorem 3.4.** *Suppose that  $n \geq 3$  and the parameters  $\frac{\alpha_1}{\alpha_n}, \dots, \frac{\alpha_{n-1}}{\alpha_n}$  are algebraically independent. There exist a not identically zero additive solution of equation (1.1) if and only if at least one of the parameters  $\frac{\beta_1}{\beta_n}, \dots, \frac{\beta_{n-1}}{\beta_n}$  is transcendental.*

#### 4. ABOUT THE REMAINING CASE

To complete the discussion we need to investigate the case when both of the collections of the parameters  $\frac{\beta_1}{\beta_n}, \dots, \frac{\beta_{n-1}}{\beta_n}$  and  $\frac{\alpha_1}{\alpha_n}, \dots, \frac{\alpha_{n-1}}{\alpha_n}$  are algebraically dependent. In case of a special functional equation of the form (1.1) we give necessary and sufficient conditions for the existence of non-trivial solutions.

**Theorem 4.1.** *Let  $n = 3$ ,  $\beta_1 = \sqrt{d_1}$ ,  $\beta_2 = \sqrt{d_2}$ ,  $\beta_3 = 1$  in (1.1) where  $d_1$  and  $d_2$  are positive rational numbers such that  $\sqrt{d_1}$  and  $\sqrt{d_2}$  are irrationals. Furthermore, suppose that  $\alpha_1\alpha_2\alpha_3 \neq 0$ . The functional equation*

$$(4.1) \quad \alpha_1 A(\sqrt{d_1}x) + \alpha_2 A(\sqrt{d_2}x) + \alpha_3 A(x) = 0$$

*has non-trivial additive solutions if and only if one of the conditions*

$$\begin{aligned} (i) \quad & 1 + \frac{\alpha_1}{\alpha_3} \sqrt{d_1} + \frac{\alpha_2}{\alpha_3} \sqrt{d_2} = 0, \\ (ii) \quad & 1 + \frac{\alpha_1}{\alpha_3} \sqrt{d_1} - \frac{\alpha_2}{\alpha_3} \sqrt{d_2} = 0, \\ (iii) \quad & 1 - \frac{\alpha_1}{\alpha_3} \sqrt{d_1} + \frac{\alpha_2}{\alpha_3} \sqrt{d_2} = 0, \\ (iv) \quad & 1 - \frac{\alpha_1}{\alpha_3} \sqrt{d_1} - \frac{\alpha_2}{\alpha_3} \sqrt{d_2} = 0. \end{aligned}$$

*is satisfied.*

*Proof.* Suppose that  $A$  is not the identically zero function. Equation (4.1) is equivalent to the equation

$$(4.2) \quad \frac{\alpha_1}{\alpha_3} A(\sqrt{d_1}x) + \frac{\alpha_2}{\alpha_3} A(\sqrt{d_2}x) + A(x) = 0.$$

Substituting  $\sqrt{d_1}x$ ,  $\sqrt{d_2}x$  and  $\sqrt{d_1 d_2}x$  in (4.2), respectively we get the system of equations which has the matrix form

$$M \begin{pmatrix} A(x) \\ A(\sqrt{d_1}x) \\ A(\sqrt{d_2}x) \\ A(\sqrt{d_1 d_2}x) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix},$$

where

$$M := \begin{pmatrix} 1 & \frac{\alpha_1}{\alpha_3} & \frac{\alpha_2}{\alpha_3} & 0 \\ d_1 \frac{\alpha_1}{\alpha_3} & 1 & 0 & \frac{\alpha_2}{\alpha_3} \\ d_2 \frac{\alpha_2}{\alpha_3} & 0 & 1 & \frac{\alpha_1}{\alpha_3} \\ 0 & d_2 \frac{\alpha_2}{\alpha_3} & d_1 \frac{\alpha_1}{\alpha_3} & 1 \end{pmatrix}.$$

Since

$$\det \begin{pmatrix} \frac{\alpha_1}{\alpha_3} & \frac{\alpha_2}{\alpha_3} & 0 \\ 1 & 0 & \frac{\alpha_2}{\alpha_3} \\ 0 & 1 & \frac{\alpha_1}{\alpha_3} \end{pmatrix} = -2 \frac{\alpha_1 \alpha_2}{\alpha_3^2} \neq 0$$

we have that the rank of  $M$  is at least 3. As  $A$  is not the identically zero function the rank of  $M$  cannot be maximal. So we may suppose that the rank of  $M$  is 3 which implies that the kernel of the transformation represented by  $M$  is one-dimensional, i.e. it is generated by a vector  $\vec{v} = (v_0, v_1, v_2, v_3)$ . This means that

$$\begin{pmatrix} A(x) \\ A(\sqrt{d_1}x) \\ A(\sqrt{d_2}x) \\ A(\sqrt{d_1 d_2}x) \end{pmatrix} = \lambda(x) \begin{pmatrix} v_0 \\ v_1 \\ v_2 \\ v_3 \end{pmatrix}$$

for some additive function  $\lambda: \mathbb{R} \rightarrow \mathbb{R}$  and  $v_0 \neq 0$ . Thus we get that

$$(4.3) \quad A(\sqrt{d_1}x) = v_1 \lambda(x) = \frac{v_1}{v_0} A(x)$$

and, in a similar way

$$(4.4) \quad A(\sqrt{d_2}x) = v_2 \lambda(x) = \frac{v_2}{v_0} A(x).$$

Both (4.3) and (4.4) has the form equation (1.2), therefore

$$\frac{v_1}{v_0} = \pm \sqrt{d_1} \quad \text{and} \quad \frac{v_2}{v_0} = \pm \sqrt{d_2}.$$

Thus one of the conditions (i), (ii), (iii) and (iv) is satisfied.

Conversely, if (i) is satisfied then, for example, let  $A(x) := x$  or  $A(x) := -x$ . As an illustration consider the case when (ii) is satisfied. Now we prove that

$$\vec{\mu} = (\sqrt{d_1}, \sqrt{d_2}) \quad \text{and} \quad \vec{\nu} = (\sqrt{d_1}, -\sqrt{d_2})$$

have the same defining ideal, i.e. the ideals

$$\mathcal{I}(\vec{\mu}) := \{ P \in \mathbb{Q}[x_1, x_2] \mid P(\sqrt{d_1}, \sqrt{d_2}) = 0 \}$$

and

$$\mathcal{I}(\vec{\nu}) := \{ P \in \mathbb{Q}[x_1, x_2] \mid P(\sqrt{d_1}, -\sqrt{d_2}) = 0 \}$$

are the same. Suppose that  $P(\sqrt{d_1}, \sqrt{d_2}) = 0$ . Then we can write  $P(\sqrt{d_1}, x_2) = f(x_2)(x_2^2 - d_2)$  because the degree of  $\sqrt{d_2}$  is 2. Therefore  $P(\sqrt{d_1}, -\sqrt{d_2}) = 0$ . The method is similar for any elements  $Q[x_1, x_2]$  of the defining ideal of  $\vec{v}$ . Therefore there exists a field isomorphism  $\delta: \mathbb{Q}(\sqrt{d_1}, \sqrt{d_2}) \rightarrow \mathbb{Q}(\sqrt{d_1}, -\sqrt{d_2})$  such that  $\delta(\sqrt{d_1}) = \sqrt{d_1}$  and  $\delta(\sqrt{d_2}) = -\sqrt{d_2}$ . For the proof see Lemma 3.1. in [4]. Now we can use the procedure of semilinear extension to construct a not identically zero additive function  $A$  such that  $A(\sqrt{d_1}x) = \sqrt{d_1}A(x)$  and  $A(\sqrt{d_2}x) = -\sqrt{d_2}A(x)$ . (See Theorem 3.2. in [4].) According to (ii) the function  $A$  is obviously satisfies (4.1). The case of (iii) and (iv) is similar.  $\square$

**Example 4.2.** The coordinates of  $(e, \frac{\sqrt{d_1}}{\sqrt{d_2}}e + \frac{1}{\sqrt{d_2}})$  are algebraically dependent over  $\mathbb{Q}$ , since the non-zero polynomial

$$P(x_1, x_2) = (d_1x_1^2 - d_2x_2^2 - 1)^2 - 4d_2x_2^2$$

vanishes at  $(e, \frac{\sqrt{d_1}}{\sqrt{d_2}}e + \frac{1}{\sqrt{d_2}})$ . Theorem 4.1. implies that if  $\frac{\alpha_1}{\alpha_3} = e$  and  $\frac{\alpha_2}{\alpha_3} = \frac{\sqrt{d_1}}{\sqrt{d_2}}e + \frac{1}{\sqrt{d_2}}$ , there exist non-trivial additive solutions of equation (4.1).

The coordinates of  $(e, \frac{\sqrt{d_1}}{\sqrt{d_2}}e)$  are algebraically dependent over  $\mathbb{Q}$ , since the non-zero polynomial  $P(x_1, x_2) = \frac{d_1}{d_2}x_1^2 - x_2^2$  vanishes at  $(e, \frac{\sqrt{d_1}}{\sqrt{d_2}}e)$ . Theorem 4.1. implies that if  $\frac{\alpha_1}{\alpha_3} = e$  and  $\frac{\alpha_2}{\alpha_3} = \frac{\sqrt{d_1}}{\sqrt{d_2}}e$  then the only additive solution of (4.1) is the identically zero function.

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