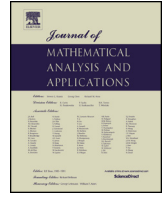




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On convexity properties with respect to a Chebyshev system [☆]

Zsolt Páles ^{a,*}, Mahmood Kamil Shihab ^{b,c}

^a *Institute of Mathematics, University of Debrecen, Hungary*

^b *Doctoral School of Mathematical and Computational Sciences, University of Debrecen, Hungary*

^c *Department of Mathematics, College of Education for Pure Sciences, University of Kirkuk, Iraq*



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ABSTRACT

The main purpose of this paper is to introduce various convexity concepts in terms of a positive Chebyshev system ω and give a systematic investigation of the relations among them. We generalize a celebrated theorem of Bernstein–Doetsch to the setting of ω -Jensen convexity. We also give sufficient conditions for the existence of discontinuous ω -Jensen affine functions. The concept of Wright convexity is extended to the setting of Chebyshev systems, as well, and it turns out to be an intermediate convexity property between ω -convexity and ω -Jensen convexity. For certain Chebyshev systems, we generalize the decomposition theorems of Wright convex and higher-order Wright convex functions obtained by C. T. Ng in 1987 and by Maksa and Páles in 2009, respectively.

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1. Introduction

Throughout this paper \mathbb{R} and \mathbb{R}_+ will denote the sets real and positive real numbers, respectively. The simplex of strictly ordered n -tuples of a set $H \subset \mathbb{R}$, denoted by $\sigma_n(H)$, is defined by

$$\sigma_n(H) := \{(x_1, \dots, x_n) \in H \mid x_1 < \dots < x_n\}.$$

Obviously, the $\sigma_n(H)$ is a nonempty set if and only if the cardinality $|H|$ of H is bigger than or equal to n . We adopt that $|H| \geq n$. Let $\omega = (\omega_1, \dots, \omega_n) : H \rightarrow \mathbb{R}^n$ be a vector-valued function, and define the functional operator $\Phi_\omega := \Phi_{(\omega_1, \dots, \omega_n)} : \sigma_n(H) \rightarrow \mathbb{R}$ by

$$\Phi_\omega(x_1, \dots, x_n) := \begin{vmatrix} \omega_1(x_1) & \dots & \omega_1(x_n) \\ \vdots & \ddots & \vdots \\ \omega_n(x_1) & \dots & \omega_n(x_n) \end{vmatrix} \quad ((x_1, \dots, x_n) \in \sigma_n(H)).$$

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* Corresponding author.

E-mail addresses: pales@science.unideb.hu (Z. Páles), mahmood.kamil@science.unideb.hu, mahmoodkamil30@uokirkuk.edu.iq (M.K. Shihab).

A continuous function ω is said to be an n -dimensional positive (respectively negative) Chebyshev system over H if Φ_ω is strictly positive (respectively, strictly negative) over $\sigma_n(H)$. The system ω is called an n -dimensional Chebyshev system over H if it is either a positive or a negative Chebyshev system over H . If $\omega : \mathbb{R} \rightarrow \mathbb{R}^n$ equals the n -dimensional standard or polynomial system $\pi_n : I \rightarrow \mathbb{R}^n$, which is defined by

$$\pi_n(t) := (1, t, \dots, t^{n-1}) \quad (t \in \mathbb{R}),$$

then, by computing Vandermonde determinants, one can easily show that it is a positive Chebyshev system. More generally, if $p_1 < \dots < p_n$ are given exponents, then one can show that the system given by

$$\mathbb{R}_+ \ni t \mapsto (t^{p_1}, \dots, t^{p_n})$$

is also a positive Chebyshev system on \mathbb{R}_+ . Important Chebyshev systems arise also related to hyperbolic and trigonometric functions. For instance, for all $n \in \mathbb{N}$, the systems given by

$$\begin{aligned} I \ni t &\mapsto (\cos(t), \sin(t), \dots, \cos(nt), \sin(nt)), \\ I \ni t &\mapsto (1, \cos(t), \sin(t), \dots, \cos(nt), \sin(nt)) \end{aligned}$$

are positive $2n$ - and $(2n+1)$ -dimensional Chebyshev systems over any nonempty open interval I with length less than or equal to π and 2π , respectively. (For the proof of these statements, see the introduction of the paper [14].) There are analogous Chebyshev systems in terms of hyperbolic functions as well. For further standard applications of Chebyshev systems, we refer to the monographs [4] and [5].

In what follows, we recall some definitions from the paper [14] (see also the paper [2] for these definitions in the polynomial setting). Let $I \subset \mathbb{R}$ be a nonvoid interval, $n \in \mathbb{N}$ and let $\omega = (\omega_1, \dots, \omega_n) : I \rightarrow \mathbb{R}^n$ be an n -dimensional positive Chebyshev system over I . For a function $f : I \rightarrow \mathbb{R}$, the functional operator $\Phi_{(\omega, f)} : \sigma_{n+1}(I) \rightarrow \mathbb{R}$ is defined by $\Phi_{(\omega, f)} := \Phi_{(\omega_1, \dots, \omega_n, f)}$.

For a given vector $t = (t_1, \dots, t_n) \in \mathbb{R}_+^n$, a function $f : I \rightarrow \mathbb{R}$ is said to be (t, ω) -convex if

$$\Phi_{(\omega, f)}(x, x + t_1 h, \dots, x + (t_1 + \dots + t_n)h) \geq 0 \quad (1)$$

holds for all $h > 0$, $x \in I$ with $x + (t_1 + \dots + t_n)h \in I$. If $T \subseteq \mathbb{R}_+$ and f is (t, ω) -convex for every $t \in T^n$, then f is called (T, ω) -convex.

If $t = (t_1, \dots, t_n) \in \mathbb{R}_+^n$ and (1) is satisfied with equality, then f is called a (t, ω) -affine function. If $T \subseteq \mathbb{R}_+$ and f is (t, ω) -affine for every $t \in T^n$, then f is called (T, ω) -affine. In particular, we say that f is ω -Jensen convex if it is $(\{1\}, \omega)$ -convex, i.e., if

$$\Phi_{(\omega, f)}(x, x + h, \dots, x + nh) \geq 0 \quad (2)$$

holds for all $h > 0$, $x \in I$ with $x + nh \in I$. If (2) is valid with equality instead of inequality, then f is said to be ω -Jensen affine.

A function f is termed ω -convex if it is (\mathbb{R}_+, ω) -convex. It is easy to see that f is ω -convex on I if and only if

$$\Phi_{(\omega, f)}(x_0, x_1, \dots, x_n) \geq 0 \quad ((x_0, x_1, \dots, x_n) \in \sigma_{n+1}(I)). \quad (3)$$

A function f is called ω -affine if (3) is satisfied with equality.

We have to mention that in the case when $\omega = \pi_n$, then the concepts of ω -convexity and ω -Jensen convexity, was introduced by Hopf [3] and Popoviciu [11] (see also the book [6] by Kuczma) and these properties were called convexity and Jensen convexity of order $(n-1)$, respectively. If a function $f : I \rightarrow \mathbb{R}$

is n times differentiable, then it is convex of order $(n - 1)$, i.e., convex with respect to the polynomial system π_n if and only if the n th derivative of f is nonnegative over I . In the particular case when $n = 2$, this is the standard characterization of convexity of twice differentiable functions.

It is a nontrivial statement whether or not ω -convex functions form a proper subclass of ω -Jensen convex functions. Depending on the Chebyshev system, the answer could be positive and negative as well. On the other hand, it is well-known that, for all $n \geq 2$, π_n -convex functions form a proper subset of π_n -Jensen convex functions. By [12, Theorem 2], it follows that, for any additive function $A : \mathbb{R} \rightarrow \mathbb{R}$ and $n \in \mathbb{N}$, the function $f := A^{n-1}$ is Jensen affine (and hence it is Jensen convex) of order $n - 1$. On the other hand, f is convex of order $n - 1$ if and only if A is continuous. Therefore, if A is discontinuous, then f cannot be convex of order $n - 1$. For a construction of a Jensen convex function of order $n - 1$ which is not Wright convex of order $n - 1$, we refer to the paper [9].

The following result shows that, for any nonempty set $T \subseteq \mathbb{R}_+$, (T, ω) -convexity implies ω -Jensen convexity.

Theorem 1.1. *Let $T \subseteq \mathbb{R}_+$ be a nonempty set. If a function $f : I \rightarrow \mathbb{R}$ is (T, ω) -convex (resp. (T, ω) -affine), then it is (\mathbb{Q}_+, ω) -convex (resp. (\mathbb{Q}_+, ω) -affine), in particular, it is ω -Jensen convex (resp. ω -Jensen affine).*

Proof. The result immediately follows from [14, Theorem 5]. \square

In section 2 we show that to any ω -Jensen convex (resp. ω -Jensen affine) function there exists a continuous ω -convex (resp. ω -affine) function so that these two functions coincide on dense subset of their domains. As a corollary, we obtain that ω -convex functions are automatically continuous. The Bernstein-Doetsch theorem is generalized to the setting of ω -convexity with respect to a positive Chebyshev system, that is, we show that an ω -Jensen convex function which is bounded over some nonempty open subinterval, is also ω -convex. We also establish characterizations of ω -Jensen affine functions in several settings. A sufficient condition on ω that ensures the existence of discontinuous ω -Jensen affine (resp. ω -Jensen convex) function is given as well. Some of the results of this section extend that of the paper [8] by Matkowski.

In Section 3, we generalize the concept of Wright convexity to ω -Wright convexity with respect to a positive Chebyshev system, and establish its relationship with ω -convexity and ω -Jensen convexity by showing that ω -Wright convexity is an intermediate property. The question whether the inclusions are proper or not remains open for the general setting. We also extend Ng’s decomposition theorem to the setting of ω -Wright convexity with respect certain positive Chebyshev systems. Finally, in the two dimensional case, we show that ω -Wright convexity could be equivalent to Wright convexity for certain positive Chebyshev systems.

2. Results on ω -Jensen functions

In what follows, if D is a subset of I and $f : D \rightarrow \mathbb{R}$, then f is said to be *locally uniformly continuous* if, for all compact subintervals $[a, b]$ of I and for all $\varepsilon > 0$, there exists $\delta > 0$ such that, for all $x, y \in [a, b] \cap D$ with $|x - y| < \delta$, we have that $|f(x) - f(y)| < \varepsilon$.

Lemma 2.1. *Let D be a subset of I and let $f : D \rightarrow \mathbb{R}$ be a locally uniformly continuous function. Then f admits a continuous extension to I . Provided that D is dense, the extension is unique.*

The verification of this lemma is standard and straightforward, therefore, we can omit it.

Theorem 2.2. *Let $n \geq 2$ and let $\omega = (\omega_1, \dots, \omega_n) : I \rightarrow \mathbb{R}^n$ be an n -dimensional positive Chebyshev system and let \mathbb{K} be a subfield of \mathbb{R} . If a function $f : I \rightarrow \mathbb{R}$ is (\mathbb{K}_+, ω) -convex (resp. (\mathbb{K}_+, ω) -affine), then there exists a continuous ω -convex (resp. ω -affine) function $g : I \rightarrow \mathbb{R}$ such that $g|_{I \cap \mathbb{K}} = f|_{I \cap \mathbb{K}}$.*

(Here, and in the sequel, \mathbb{K}_+ denotes the intersection $\mathbb{K} \cap \mathbb{R}_+$.)

Proof. If f is (\mathbb{K}_+, ω) -convex, then by definition we have the inequality

$$\Phi_{(\omega, f)}(x_0, x_1, \dots, x_n) \geq 0 \quad ((x_0, \dots, x_n) \in \sigma_{n+1}(I \cap \mathbb{K})). \quad (4)$$

Indeed, apply the inequality (1) with $x := x_0$, $h := 1$, and $t_i := x_i - x_{i-1} \in \mathbb{K}_+$. If f is assumed to be (\mathbb{K}_+, ω) -affine, then (4) is satisfied with equality.

Using the continuity of the function ω , we are going to show that the restricted function $f|_{I \cap \mathbb{K}}$ is locally uniformly continuous. To prove this let $[a, b] \subset I$ be arbitrary. Without loss of generality, we can assume that $a, b \in \mathbb{K}$. (In fact, if one of a or b is not in \mathbb{K} , then, using the density of \mathbb{K} , we can find $a', b' \in \mathbb{K} \cap I$ such that $a' < a$ and $b < b'$ and then we can work on the closed interval $[a', b']$.) We fix some elements $u_0 < u_1 < \dots < u_{n-2} < a$ and $b < v$ of the set $I \cap \mathbb{K}$. Then, for $x, y \in [a, b] \cap \mathbb{K}$ with $x < y$, we have that $(u_0, \dots, u_{n-2}, x, y), (u_0, \dots, u_{n-3}, x, y, v) \in \sigma_{n+1}(I \cap \mathbb{K})$, therefore (4) implies

$$\Phi_{(\omega, f)}(u_0, \dots, u_{n-2}, x, y) \geq 0 \quad \text{and} \quad \Phi_{(\omega, f)}(u_0, \dots, u_{n-3}, x, y, v) \geq 0. \quad (5)$$

The first of these inequalities implies that

$$\begin{vmatrix} \omega_1(u_0) & \dots & \omega_1(u_{n-2}) & \omega_1(x) & \omega_1(y) \\ \vdots & \ddots & \vdots & \vdots & \vdots \\ \omega_n(u_0) & \dots & \omega_n(u_{n-2}) & \omega_n(x) & \omega_n(y) \\ f(u_0) & \dots & f(u_{n-2}) & f(x) & f(y) \end{vmatrix} \geq 0.$$

Developing this determinant by the last row, this inequality is equivalent to

$$f(y)P(x) - f(x)P(y) \geq R(x, y) \quad ((x, y) \in \sigma_2(I \cap \mathbb{K})), \quad (6)$$

where $P : [a, b] \rightarrow \mathbb{R}$ and $R : [a, b]^2 \rightarrow \mathbb{R}$ are defined by

$$P(z) := \Phi_{\omega}(u_0, \dots, u_{n-2}, z)$$

and

$$R(x, y) := \sum_{i=0}^{n-2} (-1)^{n-1-i} f(u_i) \Phi_{\omega}(u_0, \dots, u_{i-1}, u_{i-1}, \dots, u_{n-2}, x, y)$$

For $z \in [a, b]$, we have that $(u_0, \dots, u_{n-2}, z) \in \sigma_n(I)$. Therefore, by the positivity and continuity of the Chebyshev system, it follows that P is positive and continuous over $[a, b]$. We can also see that R is continuous on $[a, b]^2$ and $R(z, z) = 0$ for all $z \in [a, b]$. Substituting $x = a$ into (6), we get that

$$f(y) \geq \frac{R(a, y) + f(a)P(y)}{P(a)} \quad (y \in [a, b] \cap \mathbb{K}).$$

The right hand side of this inequality is a continuous function of y over the compact interval $[a, b]$, therefore it is bounded from below. Hence $f|_{[a, b] \cap \mathbb{K}}$ is also bounded from below. Putting $y = b$ into (6), it follows that

$$\frac{f(b)P(x) - R(x, b)}{P(b)} \geq f(x) \quad (x \in [a, b] \cap \mathbb{K}).$$

Arguing similarly as above, this inequality yields that $f|_{[a,b] \cap \mathbb{K}}$ is bounded from above hence there exists a positive number K such that, for $x \in [a, b] \cap \mathbb{K}$, we have $|f(x)| \leq K$.

Now we consider the second inequality in (5). It can be rewritten as

$$\begin{vmatrix} \omega_1(u_0) & \dots & \omega_1(u_{n-3}) & \omega_1(x) & \omega_1(y) & \omega_1(v) \\ \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\ \omega_n(u_0) & \dots & \omega_n(u_{n-3}) & \omega_n(x) & \omega_n(y) & \omega_n(v) \\ f(u_0) & \dots & f(u_{n-3}) & f(x) & f(y) & f(v) \end{vmatrix} \geq 0.$$

Developing this determinant by its last row, this inequality is equivalent to

$$f(x)Q(y) - f(y)Q(x) \geq S(x, y) \quad ((x, y) \in \sigma_2(I \cap \mathbb{K})), \tag{7}$$

where $Q : [a, b] \rightarrow \mathbb{R}$ and $S : [a, b]^2 \rightarrow \mathbb{R}$ are defined by

$$Q(z) := \Phi_\omega(u_0, \dots, u_{n-3}, z, v)$$

and

$$S(x, y) := \sum_{i=0}^{n-3} (-1)^{n-1-i} f(u_i) \Phi_\omega(u_0, \dots, u_{i-1}, u_{i-1}, \dots, u_{n-3}, x, y, v) - f(v) \Phi_\omega(u_0, \dots, u_{n-3}, x, y).$$

The inclusion $(u_0, \dots, u_{n-3}, z, v) \in \sigma_n(I \cap \mathbb{K})$, the positivity and continuity of the Chebyshev system yield that Q is a positive and continuous function over $[a, b]$. We also have that S is continuous over $[a, b]^2$ and $S(z, z) = 0$ for all $z \in [a, b]$.

For $x, y \in [a, b] \cap \mathbb{K}$ the inequalities (6) and (7) imply that

$$\begin{aligned} f(y) - f(x) &\geq \frac{P(y) - P(x)}{P(x)} f(x) + \frac{R(x, y)}{P(x)} \geq -K \frac{|P(y) - P(x)|}{P(x)} + \frac{R(x, y)}{P(x)} =: A(x, y), \\ f(y) - f(x) &\leq \frac{Q(y) - Q(x)}{Q(x)} f(x) + \frac{S(x, y)}{Q(x)} \leq \frac{|Q(y) - Q(x)|}{Q(x)} K + \frac{S(x, y)}{Q(x)} =: B(x, y). \end{aligned} \tag{8}$$

The functions A and B defined on the right hand side of these inequalities are continuous over $[a, b]^2$ and hence they are uniformly continuous over $[a, b]^2$. Therefore, for all $\varepsilon > 0$, there exists $\delta > 0$ such that, for all $(x, y), (u, v) \in [a, b]^2$ with $\|(x, y) - (u, v)\| < \delta$, we have

$$\max(|A(x, y) - A(u, v)|, |B(x, y) - B(u, v)|) < \varepsilon.$$

In particular, if $|x - y| < \delta$, then substituting $(u, v) = (x, x)$ and using that A and B vanish at diagonal points of the square $[a, b]^2$, the above inequality implies that

$$\max(|A(x, y)|, |B(x, y)|) < \varepsilon.$$

Therefore, in view of the inequalities in (8), $x, y \in [a, b] \cap \mathbb{K}$ with $|x - y| < \delta$, we obtain that

$$|f(y) - f(x)| < \varepsilon.$$

This proves that $f|_{[a,b] \cap \mathbb{K}}$ is uniformly continuous and hence $f|_{I \cap \mathbb{K}}$ is locally uniformly continuous. If f is (\mathbb{K}_+, ω) -affine, then it is also (\mathbb{K}_+, ω) -convex, therefore we have the same conclusion.

In view of Lemma 2.1 with the dense set $D = I \cap \mathbb{K}$, there exists a continuous function $g : I \rightarrow \mathbb{R}$ such that $g(x)|_{I \cap \mathbb{K}} = f(x)|_{I \cap \mathbb{K}}$.

Finally, we show that g is ω -convex (resp. ω -affine). Let (y_0, \dots, y_n) be an arbitrary element of $\sigma_{n+1}(I)$. Then, by the density of \mathbb{K} in I , for each $j \in \{0, \dots, n\}$, there exists a sequence $(x_{k,j})_{k \in \mathbb{N}}$ in $\sigma_{n+1}(I \cap \mathbb{K})$ converging to y_j as $k \rightarrow \infty$. Then, applying the (\mathbb{K}_+, ω) -convexity (resp. the (\mathbb{K}_+, ω) -affinity) of f , we have that (4) is valid, we obtain

$$\begin{aligned} \Phi_{(\omega,g)}(x_{k,0}, x_{k,1}, \dots, x_{k,n}) &= \Phi_{(\omega,f)}(x_{k,0}, x_{k,1}, \dots, x_{k,n}) \geq 0 \\ (\text{resp. } \Phi_{(\omega,g)}(x_{k,0}, x_{k,1}, \dots, x_{k,n}) &= \Phi_{(\omega,f)}(x_{k,0}, x_{k,1}, \dots, x_{k,n}) = 0). \end{aligned}$$

By the continuity of g , the function $\Phi_{(\omega,g)}$ is continuous. Upon taking the limit $k \rightarrow \infty$, the above inequality (resp. equality) implies that

$$\Phi_{(\omega,g)}(y_0, \dots, y_n) \geq 0 \quad (\text{resp. } \Phi_{(\omega,g)}(y_0, \dots, y_n) = 0).$$

Therefore, g is ω -convex (resp. ω -affine). \square

Corollary 2.3. *Let $n \geq 2$ and $\omega = (\omega_1, \dots, \omega_n) : I \rightarrow \mathbb{R}^n$ be an n -dimensional positive Chebyshev system. If $f : I \rightarrow \mathbb{R}$ is ω -convex (resp. ω -affine), then it is continuous on I .*

Proof. The corollary follows by applying Theorem 2.2 with $\mathbb{K} := \mathbb{R}$. \square

Corollary 2.4. *Let $n \geq 2$ and $\omega = (\omega_1, \dots, \omega_n) : I \rightarrow \mathbb{R}^n$ be an n -dimensional positive Chebyshev system. If $f : I \rightarrow \mathbb{R}$ is ω -Jensen convex (resp. ω -Jensen affine), then there exists a continuous ω -convex (resp. ω -affine) function $g : I \rightarrow \mathbb{R}$ such that $g|_{I \cap \mathbb{Q}} = f|_{I \cap \mathbb{Q}}$.*

Proof. In view of Theorem 1.1, the ω -Jensen convexity (resp. ω -Jensen affinity) of f implies that it is (\mathbb{Q}_+, ω) -convex (resp. (\mathbb{Q}_+, ω) -affine). Now the statement of the corollary follows by applying Theorem 2.2 with $\mathbb{K} := \mathbb{Q}$. \square

The following statement is the extension of the celebrated Bernstein–Doetsch theorem [1] to the setting of ω -Jensen convexity.

Theorem 2.5. *If $f : I \rightarrow \mathbb{R}$ is ω -Jensen convex and bounded on a nonempty open subset of I , then it is continuous on I .*

Proof. Let U be a nonvoid open subinterval of I such that f is bounded on U by $K \geq 0$. In the first part of the proof, we are going to show that f is locally bounded on I , i.e., for every $v \in I$, there is an open set $V \subseteq I$ containing v such that f is bounded on V .

Let $v \in I$ be arbitrary. If $v \in U$, then the statement holds with $V = U$. Therefore, we may assume that $v \notin U$. Choose a closed interval $[a, b] \subset U$. Then either $v < a$ or $b < v$. We consider now the case when $v < a$.

We choose some rational numbers $a - v < r_1 < \dots < r_n < b - v$. Then we have that $v < a < v + r_1 < \dots < v + r_n < b$. One can construct a bounded neighborhood W of v such that $\overline{W} \subseteq I$ and, for all $x \in W$, we have $x < a < x + r_1 < \dots < x + r_n < b$. Now the ω -Jensen convexity of f and Theorem 1.1 yield that f is (\mathbb{Q}_+, ω) -convex, hence we can get that

$$\Phi_{\omega,f}(x, x + r_1, \dots, x + r_n) \geq 0$$

for all $x \in W$. This inequality implies that

$$\begin{vmatrix} \omega_1(x) & \omega_1(x+r_1) & \dots & \omega_1(x+r_n) \\ \vdots & \vdots & \ddots & \vdots \\ \omega_n(x) & \omega_n(x+r_1) & \dots & \omega_n(x+r_n) \\ f(x) & f(x+r_1) & \dots & f(x+r_n) \end{vmatrix} \geq 0.$$

Developing the determinant by last row, we obtain

$$\begin{aligned} & (-1)^n f(x) \Phi_\omega(x+r_1, \dots, x+r_n) \\ & + \sum_{i=1}^n (-1)^{n+i} f(x+r_i) \Phi_\omega(x, x+r_1, \dots, x+r_{i-1}, x+r_{i+1}, \dots, x+r_n) \geq 0. \end{aligned} \tag{9}$$

By the boundedness of f on U , the inclusion $x+r_i \in [a, b] \subseteq U$ we obtain that $(-1)^{n+i} f(x+r_i) \leq K$. The continuity of ω and positivity of Chebyshev system yield that the function

$$x \mapsto \sum_{i=1}^n \frac{\Phi_\omega(x, x+r_1, \dots, x+r_{i-1}, x+r_{i+1}, \dots, x+r_n)}{\Phi_\omega(x+r_1, \dots, x+r_n)}$$

is bounded from above by a positive number L over the compact set \overline{W} . Therefore, the inequality (9) implies that, for all $x \in W$,

$$(-1)^{n-1} f(x) \leq \sum_{i=1}^n (-1)^{n+i} f(x+r_i) \frac{\Phi_\omega(x, x+r_1, \dots, x+r_{i-1}, x+r_{i+1}, \dots, x+r_n)}{\Phi_\omega(x+r_1, \dots, x+r_n)} \leq KL,$$

which implies that $(-1)^{n-1} f$ is bounded from above over W .

To prove that $(-1)^{n-1} f$ is bounded from below over a neighborhood $V \subseteq W$ of v , we additionally fix $v_0 \in I$ such that $v_0 < v$. Now choose rational numbers

$$1 < \frac{a-v_0}{v-v_0} < r_2 < r_3 < \dots < r_n < \frac{b-v_0}{v-v_0}.$$

Then we have

$$a < v_0 + r_2(v-v_0) < v_0 + r_3(v-v_0) < \dots < v_0 + r_n(v-v_0) < b.$$

Now one can construct a neighborhood V of v such that $V \subseteq W$ and, for all $x \in V$, we have

$$v_0 + r_0(x-v_0) < v_0 + r_1(x-v_0) < a < v_0 + r_2(x-v_0) < \dots < v_0 + r_n(x-v_0) < b,$$

where $r_0 = 0$ and $r_1 = 1$. Again applying Theorem 1.1, we conclude that

$$\Phi_{(\omega, f)}(v_0 + r_0(x-v_0), v_0 + r_1(x-v_0), v_0 + r_2(x-v_0), \dots, v_0 + r_n(x-v_0)) \geq 0,$$

that is,

$$\Phi_{(\omega, f)}(v_0, x, v_0 + r_2(x-v_0), \dots, v_0 + r_n(x-v_0)) \geq 0,$$

for all $x \in V$. This inequality, for $x \in V$, is equivalent to

$$\begin{vmatrix} \omega_1(v_0) & \omega_1(x) & \omega_1(v_0 + r_2(x - v_0)) & \dots & \omega_1(v_0 + r_n(x - v_0)) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \omega_n(v_0) & \omega_n(x) & \omega_n(v_0 + r_2(x - v_0)) & \dots & \omega_n(v_0 + r_n(x - v_0)) \\ f(v_0) & f(x) & f(v_0 + r_2(x - v_0)) & \dots & f(v_0 + r_n(x - v_0)) \end{vmatrix} \geq 0.$$

For brevity, we write $s_i(x) := v_0 + r_i(x - v_0)$, $i \in \{2, \dots, n\}$. Developing the determinant by its last row, we obtain

$$\begin{aligned} & (-1)^n f(v_0) \Phi_\omega(x, s_2(x), \dots, s_n(x)) + (-1)^{n-1} f(x) \Phi_\omega(v_0, s_2(x), \dots, s_n(x)) \\ & + \sum_{i=2}^n (-1)^{n-i} f(s_i) \Phi_\omega(v_0, x, s_2(x) \dots, s_{i-1}(x), \dots, s_{i+1}(x), \dots, s_n(x)) \geq 0, \end{aligned}$$

which yields

$$\begin{aligned} (-1)^{n-1} f(x) & \geq (-1)^{n-1} f(v_0) \frac{\Phi_\omega(x, s_2(x), \dots, s_n(x))}{\Phi_\omega(v_0, s_2(x), \dots, s_n(x))} \\ & + \sum_{i=2}^n (-1)^{n-i-1} f(s_i) \frac{\Phi_\omega(v_0, x, s_2(x) \dots, s_{i-1}(x), \dots, s_{i+1}(x), \dots, s_n(x))}{\Phi_\omega(v_0, s_2(x), \dots, s_n(x))}. \end{aligned} \quad (10)$$

By the boundedness of f on U and the inclusion $s_i(x) \in [a, b] \subseteq U$, we get $(-1)^{n-i-1} f(s_i(x)) \geq -K$. The continuity and the positivity of Chebyshev system ω yield that the functions

$$x \mapsto \frac{\Phi_\omega(x, s_2(x), \dots, s_n(x))}{\Phi_\omega(v_0, s_2(x), \dots, s_n(x))} \quad \text{and} \quad x \mapsto \sum_{i=1}^n \frac{\Phi_\omega(v_0, x, s_2(x) \dots, s_{i-1}(x), \dots, s_{i+1}(x), \dots, s_n(x))}{\Phi_\omega(v_0, s_2(x), \dots, s_n(x))}$$

are bounded from above by positive numbers M and N , respectively, over the compact set $\bar{V} \subseteq \bar{W}$. Therefore, the inequality (10) implies, for all $x \in V$, that

$$(-1)^{n-1} f(x) \geq -|f(v_0)|M - KN,$$

which proves that $(-1)^{n-1} f$ is bounded from below over V . From the two-sided boundedness, it follows that $(-1)^{n-1} f$ is bounded over V , consequently, f is also bounded over V .

To complete the proof of the theorem, we have to verify the continuity of f at any point of I . Let $v \in I$ be arbitrary. Then, according to what we have proved in the first part, there exists a neighborhood $V \subseteq I$ of v such that f is bounded on V by K . We are going to show that f is uniformly continuous on every compact subinterval $[a, b]$ of V . This, in particular, implies the continuity of f at v .

Let $[a, b] \subseteq V$. We fix additional elements $a_1 < b_1 < \dots < a_{n-1} < b_{n-1} < a < b < a_n < b_n$ in V . Then define the function $\Psi_1 : [a_1, b_1] \times \dots \times [a_{n-1}, b_{n-1}] \times [a, b]^2 \rightarrow \mathbb{R}$ and $\Psi_2 : [a_1, b_1] \times \dots \times [a_{n-2}, b_{n-2}] \times [a, b]^2 \times [a_n, b_n] \rightarrow \mathbb{R}$ by

$$\Psi_1(v_1, \dots, v_{n-1}, x, y) := \left| 1 - \frac{\Phi_\omega(v_1, \dots, v_{n-1}, y)}{\Phi_\omega(v_1, \dots, v_{n-1}, x)} \right| + \sum_{i=1}^{n-1} \left| \frac{\Phi_\omega(v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_{n-1}, x, y)}{\Phi_\omega(v_1, \dots, v_{n-1}, x)} \right|,$$

and

$$\begin{aligned} \Psi_2(v_1, \dots, v_{n-2}, x, y, v_n) & := \left| 1 - \frac{\Phi_\omega(v_1, \dots, v_{n-2}, x, v_n)}{\Phi_\omega(v_1, \dots, v_{n-2}, y, v_n)} \right| + \frac{\Phi_\omega(v_1, \dots, v_{n-2}, x, y)}{\Phi_\omega(v_1, \dots, v_{n-2}, y, v_n)} \\ & + \sum_{i=1}^{n-2} \left| \frac{\Phi_\omega(v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_{n-2}, x, y, v_n)}{\Phi_\omega(v_1, \dots, v_{n-2}, y, v_n)} \right|. \end{aligned}$$

Then the functions Ψ_1 and Ψ_2 are continuous over a compact rectangle, therefore, they are uniformly continuous. On the other hand, $\Psi_1(v_1, \dots, v_{n-1}, x, x) = \Psi_2(v_1, \dots, v_{n-2}, x, x, v_n) = 0$ for all $x \in [a, b]$ and $(v_1, \dots, v_{n-1}, v_n) \in [a_1, b_1] \times \dots \times [a_{n-1}, b_{n-1}] \times [a_n, b_n]$.

Thus, for every $\varepsilon > 0$, there exists $\delta > 0$ such that, for all $x, y \in [a, b]$ with $|x - y| < \delta$ and for all $(v_1, \dots, v_{n-1}, v_n) \in [a_1, b_1] \times \dots \times [a_{n-1}, b_{n-1}] \times [a_n, b_n]$,

$$\begin{aligned} \Psi_1(v_1, \dots, v_{n-1}, x, y) &= \Psi_1(v_1, \dots, v_{n-1}, x, y) - \Psi_1(v_1, \dots, v_{n-1}, x, x) < \frac{\varepsilon}{K}, \\ \Psi_2(v_1, \dots, v_{n-2}, x, y, v_n) &= \Psi_2(v_1, \dots, v_{n-2}, x, y, v_n) - \Psi_2(v_1, \dots, v_{n-2}, x, x, v_n) < \frac{\varepsilon}{K}. \end{aligned}$$

Now choose $x, y \in [a, b]$ with $x < y < x + \delta$. Then choose the rational numbers $\lambda_1, \dots, \lambda_n$ such that

$$\frac{a_i - x}{y - x} < \lambda_i < \frac{b_i - x}{y - x}, \quad i \in \{1, \dots, n\}.$$

Then, with the notation $v_i := (1 - \lambda_i)x + \lambda_i y$, we have that

$$a_i < v_i < b_i, \quad i \in \{1, \dots, n\}.$$

First define

$$r_i := \frac{v_i - v_1}{y - v_1} \quad (i \in \{1, \dots, n - 1\}), \quad r_n := \frac{x - v_1}{y - v_1}, \quad r_{n+1} := \frac{y - v_1}{y - v_1}.$$

Clearly, due to the chain of inequalities $v_1 < v_2 \dots < v_{n-1} < x < y$, we have that $r_1 = 0 < r_2 < \dots < r_n < r_{n+1} = 1$. On the other hand, for $i \in \{1, \dots, n - 1\}$,

$$r_i = \frac{v_i - v_1}{y - v_1} = \frac{(1 - \lambda_i)x + \lambda_i y - ((1 - \lambda_1)x + \lambda_1 y)}{y - ((1 - \lambda_1)x + \lambda_1 y)} = \frac{(\lambda_i - \lambda_1)(y - x)}{(1 - \lambda_1)(y - x)} = \frac{\lambda_i - \lambda_1}{1 - \lambda_1} \in \mathbb{Q},$$

and

$$r_n = \frac{x - v_1}{y - v_1} = \frac{x - ((1 - \lambda_1)x + \lambda_1 y)}{y - ((1 - \lambda_1)x + \lambda_1 y)} = \frac{\lambda_1(x - y)}{(1 - \lambda_1)(y - x)} = \frac{-\lambda_1}{1 - \lambda_1} \in \mathbb{Q}.$$

Using Theorem 1.1, the ω -Jensen convexity of f implies that

$$\Phi_{(\omega, f)}(v_1 + r_1(y - v_1), \dots, v_1 + r_{n-1}(y - v_1), v_1 + r_n(y - v_1), v_1 + r_{n+1}(y - v_1)) \geq 0,$$

which, according to the definition of the numbers $r_1, r_2, \dots, r_n, r_{n+1}$, yields that

$$\Phi_{(\omega, f)}(v_1, \dots, v_{n-1}, x, y) \geq 0.$$

Now from the above inequality, we get

$$\begin{vmatrix} \omega_1(v_1) & \dots & \omega_1(v_{n-1}) & \omega_1(x) & \omega_1(y) \\ \vdots & \ddots & \vdots & \vdots & \vdots \\ \omega_n(v_1) & \dots & \omega_n(v_{n-1}) & \omega_n(x) & \omega_n(y) \\ f(v_1) & \dots & f(v_{n-1}) & f(x) & f(y) \end{vmatrix} \geq 0.$$

Developing this determinant by the last row, we obtain

$$f(y)\Phi_\omega(v_1, \dots, v_{n-1}, x) - f(x)\Phi_\omega(v_1, \dots, v_{n-1}, y) + \sum_{i=1}^{n-1} (-1)^{n-i-1} f(v_i)\Phi_\omega(v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_{n-1}, x, y) \geq 0.$$

By the positivity of Chebyshev system and the boundedness of f over V , the above inequality yields

$$\begin{aligned} f(x) - f(y) &\leq f(x) \left(1 - \frac{\Phi_\omega(v_1, \dots, v_{n-1}, y)}{\Phi_\omega(v_1, \dots, v_{n-1}, x)} \right) \\ &\quad + \sum_{i=1}^{n-1} (-1)^{n-i-1} f(v_i) \frac{\Phi_\omega(v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_{n-1}, x, y)}{\Phi_\omega(v_1, \dots, v_{n-1}, x)} \\ &\leq K\Psi_1(v_1, \dots, v_{n-1}, x, y) < \varepsilon. \end{aligned} \tag{11}$$

Secondly define

$$s_i := \frac{v_i - v_1}{v_n - v_1} \quad (i \in \{1, \dots, n-2\} \cup \{n\}), \quad s'_{n-1} := \frac{x - v_1}{v_n - v_1}, \quad s''_{n-1} := \frac{y - v_1}{v_n - v_1}.$$

Due to the chain inequalities $v_1 < v_2 < \dots < v_{n-2} < x < y < v_n$, we have that $s_1 = 0 < s_2 < \dots < s'_{n-1} < s''_{n-1} < s_n = 1$. On the other hand, for $i \in \{1, \dots, n-2\} \cup \{n\}$,

$$\begin{aligned} s_i &= \frac{v_i - v_1}{v_n - v_1} = \frac{(1 - \lambda_i)x + \lambda_i y - ((1 - \lambda_1)x + \lambda_1 y)}{(1 - \lambda_n)x + \lambda_n y - ((1 - \lambda_1)x + \lambda_1 y)} = \frac{(\lambda_i - \lambda_1)(y - x)}{(\lambda_n - \lambda_1)(y - x)} = \frac{\lambda_i - \lambda_1}{\lambda_n - \lambda_1} \in \mathbb{Q}, \\ s'_{n-1} &= \frac{x - v_1}{v_n - v_1} = \frac{x - ((1 - \lambda_1)x + \lambda_1 y)}{(1 - \lambda_n)x + \lambda_n y - ((1 - \lambda_1)x + \lambda_1 y)} = \frac{-\lambda_1(y - x)}{(\lambda_n - \lambda_1)(y - x)} = \frac{-\lambda_1}{\lambda_n - \lambda_1} \in \mathbb{Q} \end{aligned}$$

and

$$s''_{n-1} = \frac{y - v_1}{v_n - v_1} = \frac{y - ((1 - \lambda_1)x + \lambda_1 y)}{(1 - \lambda_n)x + \lambda_n y - ((1 - \lambda_1)x + \lambda_1 y)} = \frac{(1 - \lambda_1)(y - x)}{(\lambda_n - \lambda_1)(y - x)} = \frac{1 - \lambda_1}{\lambda_n - \lambda_1} \in \mathbb{Q}.$$

Now using Theorem 1.1, the ω -Jensen convexity of f implies that

$$\Phi_{(\omega, f)}(v_1 + s_1(v_n - v_1), \dots, v_1 + s'_{n-1}(v_n - v_1), v_1 + s''_{n-1}(v_n - v_1), v_1 + s_n(v_n - v_1)) \geq 0,$$

which, according to the definition of the numbers $s_1, s_2, \dots, s'_{n-1}, s''_{n-1}, s_n$, yields that

$$\Phi_{(\omega, f)}(v_1, \dots, v_{n-2}, x, y, v_n) \geq 0.$$

This inequality can be written as

$$\begin{vmatrix} \omega_1(v_1) & \dots & \omega_1(v_{n-2}) & \omega_1(x) & \omega_1(y) & \omega_1(v_n) \\ \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\ \omega_n(v_1) & \dots & \omega_n(v_{n-2}) & \omega_n(x) & \omega_n(y) & \omega_n(v_n) \\ f(v_1) & \dots & f(v_{n-2}) & f(x) & f(y) & f(v_n) \end{vmatrix} \geq 0.$$

Developing this determinant by the last row, we obtain

$$\begin{aligned} f(v_n)\Phi_\omega(v_1, \dots, v_{n-2}, x, y) - f(y)\Phi_\omega(v_1, \dots, v_{n-2}, x, v_n) + f(x)\Phi_\omega(v_1, \dots, v_{n-2}, y, v_n) \\ + \sum_{i=1}^{n-2} (-1)^{n-i-1} f(v_i)\Phi_\omega(v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_{n-2}, x, y, v_n) \geq 0, \end{aligned}$$

by the positivity of Chebyshev system, the above inequality is equivalent to

$$\begin{aligned}
 f(y) - f(x) &\leq f(y) \left(1 - \frac{\Phi_\omega(v_1, \dots, v_{n-2}, x, v_n)}{\Phi_\omega(v_1, \dots, v_{n-2}, y, v_n)} \right) + f(v_n) \frac{\Phi_\omega(v_1, \dots, v_{n-2}, x, y)}{\Phi_\omega(v_1, \dots, v_{n-2}, y, v_n)} \\
 &\quad + \sum_{i=1}^{n-2} (-1)^{n-i-1} f(v_i) \frac{\Phi_\omega(v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_{n-2}, x, y, v_n)}{\Phi_\omega(v_1, \dots, v_{n-2}, y, v_n)} \\
 &\leq K \Psi_2(v_1, \dots, v_{n-2}, x, y, v_n) < \epsilon.
 \end{aligned} \tag{12}$$

Hence the inequalities (11) and (12) imply that, for all $x, y \in [a, b]$ with $|x - y| < \delta$,

$$|f(x) - f(y)| < \epsilon$$

holds. This proves that f is uniformly continuous on $[a, b]$. The closed interval $[a, b] \subseteq V$ was arbitrary, therefore f is continuous on V . \square

Theorem 2.6. *Let $f : I \rightarrow \mathbb{R}$ be a function which is bounded on a nonempty open subset of I . Then it is ω -Jensen affine if and only if $f = \alpha_1 \omega_1 + \dots + \alpha_n \omega_n$ for some $\alpha_1, \dots, \alpha_n \in \mathbb{R}$.*

Proof. Assume first that f is an ω -Jensen affine function. Then, it is ω -Jensen convex, and using Theorem 2.5, it follows that f is continuous on I . We show first that, for all $x_0, x_1, \dots, x_n \in I$,

$$\Phi_{\omega, f}(x_0, x_1, \dots, x_n) = 0. \tag{13}$$

Indeed, if two of points x_0, x_1, \dots, x_n coincide, then this equality is obvious. We may assume that these points are pairwise distinct moreover that $x_0 < x_1 < \dots < x_n$. Let $0 < r_{1,k} < \dots < r_{n,k}$ be rational sequences converging to $0 < x_1 - x_0 < \dots < x_n - x_0$, respectively. Then, according to Theorem 1.1, the ω -Jensen affinity of f , for all $k \in \mathbb{N}$, yields that

$$\Phi_{\omega, f}(x_0, x_0 + r_{1,k}, \dots, x_0 + r_{n,k}) = 0.$$

Using the continuity of f and taking the limit $k \rightarrow \infty$, it follows that (13) holds.

Let us fix $x_1 < \dots < x_n$ in I arbitrarily. Then,

$$\Phi_{\omega, f}(x, x_1, \dots, x_n) = 0$$

holds for all $x \in I$, i.e.,

$$\begin{vmatrix}
 \omega_1(x) & \omega_1(x_1) & \dots & \omega_1(x_n) \\
 \vdots & \vdots & \ddots & \vdots \\
 \omega_n(x) & \omega_n(x_1) & \dots & \omega_n(x_n) \\
 f(x) & f(x_1) & \dots & f(x_n)
 \end{vmatrix} = 0.$$

Developing this determinant by the first column, we obtain

$$\sum_{i=1}^n (-1)^{i-1} \omega_i(x) \Phi_{\omega_1, \dots, \omega_{i-1}, \omega_{i+1}, \dots, \omega_n, f}(x_1, \dots, x_n) + (-1)^n f(x) \Phi_\omega(x_1, \dots, x_n) = 0.$$

Therefore,

$$f(x) = \sum_{i=1}^n (-1)^{n-i} \frac{\Phi_{\omega_1, \dots, \omega_{i-1}, \omega_{i+1}, \dots, \omega_n, f}(x_1, \dots, x_n)}{\Phi_{\omega}(x_1, \dots, x_n)} \omega_i(x).$$

Now, with an obvious choice of $\alpha_1, \dots, \alpha_n \in \mathbb{R}$, we can see that $f = \alpha_1 \omega_1 + \dots + \alpha_n \omega_n$ holds.

The reversed statement is obvious, if f is a linear combination of the coordinate functions of ω , then $\Phi_{\omega, f}$ is identically zero by standard properties of determinants. \square

The following question seems to be important: What is a necessary and sufficient condition on ω that ensures the existence of discontinuous ω -Jensen affine or discontinuous ω -Jensen convex functions? The following result provides a sufficient condition. To formulate and prove this condition, we need the following lemma.

Lemma 2.7. *Let $\omega : I \rightarrow \mathbb{R}^n$ be a positive Chebyshev system. Assume that there exist a positive continuous function $\omega_0 : I \rightarrow \mathbb{R}_+$ and a matrix $M = (a_{i,j})_{1 \leq i \leq n, 0 \leq j \leq n-1} \in \mathbb{R}^{n \times n}$ such that*

$$\omega_i(x) = (a_{i,n-1}x^{n-1} + \dots + a_{i,1}x + a_{i,0}) \cdot \omega_0(x) \quad (x \in I, i \in \{1, \dots, n\}). \quad (14)$$

Then $\det(M) > 0$ and, for all $(x_1, \dots, x_n) \in \sigma_n(I)$,

$$\Phi_{\omega}(x_1, \dots, x_n) = \omega_0(x_1) \cdots \omega_0(x_n) \cdot \det(M) \cdot \Phi_{\pi_n}(x_1, \dots, x_n). \quad (15)$$

Additionally, let $f : I \rightarrow \mathbb{R}$. Then, for all $(x_0, \dots, x_n) \in \sigma_{n+1}(I)$,

$$\Phi_{\omega, f}(x_0, \dots, x_n) = \omega_0(x_0) \cdots \omega_0(x_n) \cdot \det(M) \cdot \Phi_{\pi_n, f/\omega_0}(x_0, \dots, x_n). \quad (16)$$

Proof. The equality in (14) and the product rule for determinants imply, for all $(x_1, \dots, x_n) \in \sigma_n(I)$, that

$$\begin{aligned} & \Phi_{\omega}(x_1, \dots, x_n) \\ &= \begin{vmatrix} (a_{1,n-1}x_1^{n-1} + \dots + a_{1,1}x_1 + a_{1,0})\omega_0(x_1) & \cdots & (a_{1,n-1}x_n^{n-1} + \dots + a_{1,1}x_n + a_{1,0})\omega_0(x_n) \\ \vdots & \ddots & \vdots \\ (a_{n,n-1}x_1^{n-1} + \dots + a_{n,1}x_1 + a_{n,0})\omega_0(x_1) & \cdots & (a_{n,n-1}x_n^{n-1} + \dots + a_{n,1}x_n + a_{n,0})\omega_0(x_n) \end{vmatrix} \\ &= \omega_0(x_1) \cdots \omega_0(x_n) \begin{vmatrix} a_{1,n-1}x_1^{n-1} + \dots + a_{1,1}x_1 + a_{1,0} & \cdots & a_{1,n-1}x_n^{n-1} + \dots + a_{1,1}x_n + a_{1,0} \\ \vdots & \ddots & \vdots \\ a_{n,n-1}x_1^{n-1} + \dots + a_{n,1}x_1 + a_{n,0} & \cdots & a_{n,n-1}x_n^{n-1} + \dots + a_{n,1}x_n + a_{n,0} \end{vmatrix} \\ &= \omega_0(x_1) \cdots \omega_0(x_n) \begin{vmatrix} a_{1,0} & \cdots & a_{1,n-1} \\ \vdots & \ddots & \vdots \\ a_{n,0} & \cdots & a_{n,n-1} \end{vmatrix} \cdot \begin{vmatrix} x_1^0 & \cdots & x_n^0 \\ \vdots & \ddots & \vdots \\ x_1^{n-1} & \cdots & x_n^{n-1} \end{vmatrix} \\ &= \omega_0(x_1) \cdots \omega_0(x_n) \det(M) \cdot \Phi_{\pi_n}(x_1, \dots, x_n), \end{aligned}$$

which proves (15).

The value of the determinant $\Phi_{\pi_n}(x_1, \dots, x_n)$ equals $\prod_{1 \leq i < j \leq n} (x_j - x_i) > 0$ (because it is of Vandermonde-type). Therefore, the positivity of the Chebyshev system ω , the positivity of the function ω_0 and the equality (15) yield that $\det(M) > 0$.

The equalities in (14) and the product rule for determinants again imply, for all $(x_0, \dots, x_n) \in \sigma_{n+1}(I)$, that

$$\begin{aligned}
 & \Phi_{\omega, f}(x_0, \dots, x_n) \\
 &= \begin{vmatrix} (a_{1,n-1}x_0^{n-1} + \dots + a_{1,1}x_0 + a_{1,0})\omega_0(x_0) & \dots & (a_{1,n-1}x_n^{n-1} + \dots + a_{1,1}x_n + a_{1,0})\omega_0(x_n) \\ \vdots & \ddots & \vdots \\ (a_{n,n-1}x_0^{n-1} + \dots + a_{n,0}x_1 + a_{n,0})\omega_0(x_0) & \dots & (a_{n,n-1}x_n^{n-1} + \dots + a_{n,1}x_n + a_{n,0})\omega_0(x_n) \\ & & f(x_0) \quad \dots \quad f(x_n) \end{vmatrix} \\
 &= \omega_0(x_0) \cdots \omega_0(x_n) \begin{vmatrix} a_{1,n-1}x_0^{n-1} + \dots + a_{1,1}x_0 + a_{1,0} & \dots & a_{1,n-1}x_n^{n-1} + \dots + a_{1,1}x_n + a_{1,0} \\ \vdots & \ddots & \vdots \\ a_{n,n-1}x_0^{n-1} + \dots + a_{n,1}x_0 + a_{n,0} & \dots & a_{n,n-1}x_n^{n-1} + \dots + a_{n,1}x_n + a_{n,0} \\ & & \frac{f}{\omega_0}(x_0) \quad \dots \quad \frac{f}{\omega_0}(x_n) \end{vmatrix} \\
 &= \omega_0(x_0) \cdots \omega_0(x_n) \begin{vmatrix} a_{1,0} & \dots & a_{1,n-1} & 0 \\ \vdots & \ddots & \vdots & \\ a_{n,0} & \dots & a_{n,n-1} & 0 \\ 0 & \dots & 0 & 1 \end{vmatrix} \cdot \begin{vmatrix} x_0^0 & \dots & x_n^0 \\ \vdots & \ddots & \vdots \\ x_0^{n-1} & \dots & x_n^{n-1} \\ \frac{f}{\omega_0}(x_0) & \dots & \frac{f}{\omega_0}(x_n) \end{vmatrix} \\
 &= \omega_0(x_0) \cdots \omega_0(x_n) \cdot \det(M) \cdot \Phi_{\pi_n, f/\omega_0}(x_0, \dots, x_n),
 \end{aligned}$$

which shows the validity of (16). \square

Theorem 2.8. Assume that there exist a positive continuous function $\omega_0 : I \rightarrow \mathbb{R}_+$ and a matrix $M = (a_{i,j})_{1 \leq i \leq n, 0 \leq j \leq n-1} \in \mathbb{R}^{n \times n}$ such that (14) holds. Then $f : I \rightarrow \mathbb{R}$ is an ω -Jensen convex (resp. ω -Jensen affine) function if and only if $\frac{f}{\omega_0}$ is a π_n -Jensen convex (resp. π_n -Jensen affine) function.

Proof. According to formula (16) of Lemma 2.7, for all $h > 0$ and $x \in I \cap (I - nh)$, we have that

$$\Phi_{\omega, f}(x, x + h, \dots, x + nh) = \prod_{i=0}^n \omega_0(x + ih) \cdot \det(M) \cdot \Phi_{\pi_n, f/\omega_0}(x, x + h, \dots, x + nh).$$

Due to the positivity of $\det(M)$ and the positivity of the function ω_0 , it follows that the inequality $\Phi_{\omega, f}(x, x + h, \dots, x + nh) \geq 0$ holds if and only if $\Phi_{\pi_n, f/\omega_0}(x, x + h, \dots, x + nh) \geq 0$ is valid. This shows that f is ω -Jensen convex if and only if $\frac{f}{\omega_0}$ is π_n -Jensen convex.

Similarly, $\Phi_{\omega, f}(x, x + h, \dots, x + nh) = 0$ if and only if $\Phi_{\pi_n, f/\omega_0}(x, x + h, \dots, x + nh) = 0$, which proves that f is ω -Jensen affine if and only if $\frac{f}{\omega_0}$ is π_n -Jensen affine. \square

We need to recall the following characterization of π_n -Jensen affine functions.

Theorem 2.9. A function $f : I \rightarrow \mathbb{R}$ is π_n -Jensen affine if and only if there exist a constant $A_0 \in \mathbb{R}$, an additive function $A_1 : \mathbb{R} \rightarrow \mathbb{R}$, a symmetric biadditive function $A_2 : \mathbb{R}^2 \rightarrow \mathbb{R}$, ..., and a symmetric $(n - 1)$ -additive function $A_{n-1} : \mathbb{R}^{n-1} \rightarrow \mathbb{R}$ such that

$$f(x) = A_{n-1}(x, \dots, x) + \dots + A_2(x, x) + A_1(x) + A_0 \quad (x \in I). \tag{17}$$

Corollary 2.10. Assume that there exist a positive continuous function $\omega_0 : I \rightarrow \mathbb{R}_+$ and a matrix $(a_{i,j})_{1 \leq i \leq n, 0 \leq j \leq n-1} \in \mathbb{R}^{n \times n}$ such that (14) holds. Then $f : I \rightarrow \mathbb{R}$ is an ω -Jensen affine function if and only if there exist a constant $A_0 \in \mathbb{R}$, an additive function $A_1 : \mathbb{R} \rightarrow \mathbb{R}$, a symmetric biadditive function $A_2 : \mathbb{R}^2 \rightarrow \mathbb{R}$, ..., and a symmetric $(n - 1)$ -additive function $A_{n-1} : \mathbb{R}^{n-1} \rightarrow \mathbb{R}$ such that

$$f(x) = (A_{n-1}(x, \dots, x) + \dots + A_2(x, x) + A_1(x) + A_0)\omega_0(x) \quad (x \in I). \tag{18}$$

Proof. Assume first that f is ω -Jensen affine. Then, by Theorem 2.8, $\frac{f}{\omega_0}$ is π_n -Jensen affine. Hence, according to Theorem 2.9, there exist a constant $A_0 \in \mathbb{R}$, and additive function $A_1 : \mathbb{R} \rightarrow \mathbb{R}$, a symmetric biadditive function $A_2 : \mathbb{R}^2 \rightarrow \mathbb{R}$, ..., a symmetric $(n - 1)$ -additive function $A_{n-1} : \mathbb{R}^{n-1} \rightarrow \mathbb{R}$ such that

$$\frac{f}{\omega_0}(x) = A_{n-1}(x, \dots, x) + \dots + A_2(x, x) + A_1(x) + A_0 \quad (x \in I).$$

This proves that f is of the form (18).

To prove the reversed implication, assume that there exist a constant $A_0 \in \mathbb{R}$, and additive function $A_1 : \mathbb{R} \rightarrow \mathbb{R}$, a symmetric biadditive function $A_2 : \mathbb{R}^2 \rightarrow \mathbb{R}$, ..., a symmetric $(n - 1)$ -additive function $A_{n-1} : \mathbb{R}^{n-1} \rightarrow \mathbb{R}$ such that (18) holds. Then, according to Theorem 2.9, $\frac{f}{\omega_0}$ is a π_n -Jensen affine function. In view of Theorem 2.8, this implies that f is ω -Jensen affine. \square

3. Wright convexity with respect to extended Chebyshev systems

In 1954, Wright [17] introduced a concept of convexity which is stronger than Jensen convexity and weaker than convexity. A function $f : I \rightarrow \mathbb{R}$ is called *Wright convex* if

$$f(tx + (1 - t)y) + f((1 - t)x + ty) \leq f(x) + f(y) \quad (x, y \in I, t \in [0, 1]).$$

One can easily see that convexity implies Wright convexity, and, by putting $t = \frac{1}{2}$ into the above inequality, we can see that Jensen convexity is a consequence of Wright convexity.

A characterization and the ultimate understanding of Wright convexity was established by Ng [10], who proved that $f : I \rightarrow \mathbb{R}$ is Wright convex if and only if it is of the form $f = g + A|_I$, where $g : I \rightarrow \mathbb{R}$ is convex and $A : \mathbb{R} \rightarrow \mathbb{R}$ is additive. If A is discontinuous, then f will be discontinuous and hence cannot be convex. On the other hand, if A is a discontinuous additive function, then $|A|$ is Jensen convex but not Wright convex.

The concept of Wright convexity is closely related to Schur convexity, sometimes it is termed ultramodularity and has applications, for instance, in the theory of copulas and t -norms (see [16] and the references there in).

A higher-order generalization of Wright convexity was introduced by Gilányi and Páles [2] as follows. In this paper, a function $f : I \rightarrow \mathbb{R}$ was called *Wright convex of order $(n - 1)$* , if

$$\Delta_{h_1} \cdots \Delta_{h_n} f(x) \geq 0$$

holds for all $h_1, \dots, h_n > 0$ and $x \in I \cap (I - (h_1 + \dots + h_n))$. One can easily see that Wright convexity of order 1 is equivalent to Wright convexity in the standard sense.

In what follows, we extend the notion of higher-order Wright convexity to the setting of positive Chebyshev systems. Let $\omega = (\omega_1, \dots, \omega_n) : I \rightarrow \mathbb{R}^n$ be a positive n -dimensional Chebyshev system. We say that $\bar{\omega} : I \rightarrow \mathbb{R}^{n+1}$ is an extension of ω if there exists a continuous function $\omega_{n+1} : I \rightarrow \mathbb{R}$ such that $\bar{\omega} := (\omega_1, \dots, \omega_n, \omega_{n+1})$ and $\bar{\omega}$ is a positive $(n + 1)$ -dimensional Chebyshev system.

Let ω be a positive n -dimensional Chebyshev system and $\bar{\omega}$ be an arbitrarily fixed extension of ω . We say that a function $f : I \rightarrow \mathbb{R}$ is $\bar{\omega}$ -Wright convex if, for all $h_1, \dots, h_n > 0$ and $x \in I \cap (I - (h_1 + \dots + h_n))$, the inequality

$$\sum_{(i_1, \dots, i_n)} \frac{\Phi_{(\omega, f)}(x, x + h_{i_1}, \dots, x + h_{i_1} + \dots + h_{i_n})}{\Phi_{\bar{\omega}}(x, x + h_{i_1}, \dots, x + h_{i_1} + \dots + h_{i_n})} \geq 0 \tag{19}$$

holds, where the summation is taken over all permutation (i_1, \dots, i_n) of the elements $\{1, \dots, n\}$.

Our first result establishes the connections between ω -convexity, $\bar{\omega}$ -Wright convexity and ω -Jensen convexity.

Theorem 3.1. *Let ω be a positive n -dimensional Chebyshev system and $\bar{\omega}$ be an extension of ω . Then every ω -convex function is $\bar{\omega}$ -Wright convex and every $\bar{\omega}$ -Wright convex function is ω -Jensen convex.*

Proof. Assume first that $f : I \rightarrow \mathbb{R}$ is ω -convex. Then, for all $h_1, \dots, h_n > 0$ and $x \in I \cap (I - (h_1 + \dots + h_n))$ all permutation (i_1, \dots, i_n) of the elements $\{1, \dots, n\}$, we have that

$$\Phi_{(\omega,f)}(x, x + h_{i_1}, \dots, x + h_{i_1} + \dots + h_{i_n}) \geq 0.$$

On the other hand, by the positivity of the Chebyshev system $\bar{\omega}$, we also have that

$$\Phi_{\bar{\omega}}(x, x + h_{i_1}, \dots, x + h_{i_1} + \dots + h_{i_n}) > 0.$$

These inequalities yield that (19) is valid on the domain indicated and hence f is $\bar{\omega}$ -Wright convex.

To verify the second assertion, assume that $f : I \rightarrow \mathbb{R}$ is $\bar{\omega}$ -Wright convex. Taking $h_1 := \dots = h_n := h > 0$ in inequality (19), for all $h > 0$ and $x \in I \cap (I - nh)$, we obtain that

$$\frac{\Phi_{(\omega,f)}(x, x + h, \dots, x + nh)}{\Phi_{\bar{\omega}}(x, x + h, \dots, x + nh)} \geq 0. \tag{20}$$

Due to the positivity of the Chebyshev system $\bar{\omega}$, it follows that $\Phi_{\bar{\omega}}(x, x + h, \dots, x + nh)$ is positive, therefore, we can conclude that $\Phi_{(\omega,f)}(x, x + h, \dots, x + nh) \geq 0$, which shows that f is ω -Jensen convex. \square

The next theorem describes the connection between $\bar{\omega}$ -Wright convexity and Wright convexity of order $(n - 1)$. In what follows, the symbol $[x_0, x_1, \dots, x_n, g]$ denotes the standard n th-order divided difference of a function $g : I \rightarrow \mathbb{R}$ at the pairwise distinct nodes $x_1, x_1, \dots, x_n \in I$.

Theorem 3.2. *Assume that there exist a positive continuous function $\omega_0 : I \rightarrow \mathbb{R}_+$ and a matrix $M := (a_{i,j})_{1 \leq i \leq n, 0 \leq j \leq n-1} \in \mathbb{R}^{n \times n}$ such that (14) holds. Define $\omega_{n+1} : I \rightarrow \mathbb{R}$ by $\omega_{n+1}(t) := t^n \omega_0(t)$. Then $\bar{\omega} := (\omega, \omega_{n+1})$ is an extension of the Chebyshev system ω . In addition, we have the following assertions:*

(i) *For all $(x_0, x_1, \dots, x_n) \in \sigma_{n+1}(I)$, the equality*

$$\frac{\Phi_{(\omega,f)}(x_0, x_1, \dots, x_n)}{\Phi_{\bar{\omega}}(x_0, x_1, \dots, x_n)} = [x_0, x_1, \dots, x_n; f/\omega_0] \tag{21}$$

holds. Furthermore, a function $f : I \rightarrow \mathbb{R}$ is ω -convex if and only if f/ω_0 is convex of order $(n - 1)$.

(ii) *For all $h_1, \dots, h_n > 0$ and $x \in I \cap (I - (h_1 + \dots + h_n))$, the equality*

$$\sum_{(i_1, \dots, i_n)} \frac{\Phi_{(\omega,f)}(x, x + h_{i_1}, \dots, x + h_{i_1} + \dots + h_{i_n})}{\Phi_{\bar{\omega}}(x, x + h_{i_1}, \dots, x + h_{i_1} + \dots + h_{i_n})} = \frac{\Delta_{h_1} \cdots \Delta_{h_n}(f/\omega_0)(x)}{h_1 \cdots h_n} \tag{22}$$

holds. Furthermore, a function $f : I \rightarrow \mathbb{R}$ is $\bar{\omega}$ -Wright convex if and only if f/ω_0 is Wright convex of order $(n - 1)$.

Proof. We first verify that $\bar{\omega} = (\omega, \omega_{n+1})$ is a positive Chebyshev system. Let $(x_0, x_1, \dots, x_n) \in \sigma_{n+1}(I)$. Then, applying the equality (16) of Lemma 2.7 with $f := \omega_{n+1}$, we get

$$\begin{aligned}\Phi_{\bar{\omega}}(x_0, x_1, \dots, x_n) &= \omega_0(x_0) \cdots \omega_0(x_n) \cdot \det(M) \cdot \Phi_{(\pi_n, \omega_{n+1}/\omega_0)}(x_0, x_1, \dots, x_n) \\ &= \omega_0(x_0) \cdots \omega_0(x_n) \cdot \det(M) \cdot \Phi_{\pi_{n+1}}(x_0, x_1, \dots, x_n) > 0.\end{aligned}\tag{23}$$

The last inequality is due to the fact that $\Phi_{\pi_{n+1}}(x_0, x_1, \dots, x_n)$ is a Vandermonde determinant and $x_0 < x_1 < \cdots < x_n$. This proves that $\bar{\omega}$ is a positive Chebyshev system, indeed.

In the rest of the proof denote $g := f/\omega_0$. To show that assertion (i) holds, let $(x_0, x_1, \dots, x_n) \in \sigma_{n+1}(I)$ be fixed. In view of the Lemma 2.7, we have the equality (16). Combining this equality with (23), we can obtain

$$\frac{\Phi_{(\omega, f)}(x_0, x_1, \dots, x_n)}{\Phi_{\bar{\omega}}(x_0, x_1, \dots, x_n)} = \frac{\Phi_{(\pi_n, g)}(x_0, x_1, \dots, x_n)}{\Phi_{\pi_{n+1}}(x_0, x_1, \dots, x_n)}.$$

From the theory of divided differences, we have the identity

$$\frac{\Phi_{(\pi_n, g)}(x_0, x_1, \dots, x_n)}{\Phi_{\pi_{n+1}}(x_0, x_1, \dots, x_n)} = [x_0, x_1, \dots, x_n; g],$$

which, together with the previous equality shows that (21) holds.

The function f is $\bar{\omega}$ -convex if and only if, for all $(x_0, x_1, \dots, x_n) \in \sigma_{n+1}(I)$, the left hand side of (21) is nonnegative. According to this equality, this happens if and only if the right hand side is nonnegative, i.e., if f/ω_0 is convex of order $(n-1)$.

To show assertion (ii), let $h_1, \dots, h_n > 0$ and $x \in I \cap (I - (h_1 + \cdots + h_n))$ be fixed. Therefore, with the substitutions $x_j := x + h_1 + \cdots + h_j$, (where $j \in \{0, \dots, n\}$), (21) implies that

$$\frac{\Phi_{(\omega, f)}(x, x + h_1, \dots, x + h_1 + \cdots + h_n)}{\Phi_{\bar{\omega}}(x, x + h_1, \dots, x + h_1 + \cdots + h_n)} = [x, x + h_1, \dots, x + h_1 + \cdots + h_n; g].$$

Applying this equality for $(h_{i_1}, \dots, h_{i_n})$ (instead of (h_1, \dots, h_n)), where (i_1, \dots, i_n) is an arbitrary permutation of $(1, \dots, n)$, we can see that

$$\sum_{(i_1, \dots, i_n)} \frac{\Phi_{(\omega, f)}(x, x + h_{i_1}, \dots, x + h_{i_1} + \cdots + h_{i_n})}{\Phi_{\bar{\omega}}(x, x + h_{i_1}, \dots, x + h_{i_1} + \cdots + h_{i_n})} = \sum_{(i_1, \dots, i_n)} [x, x + h_{i_1}, \dots, x + h_{i_1} + \cdots + h_{i_n}; g].$$

On the other hand, from the paper [2], we have that

$$\sum_{(i_1, \dots, i_n)} [x, x + h_{i_1}, \dots, x + h_{i_1} + \cdots + h_{i_n}; g] = \frac{\Delta_{h_1} \cdots \Delta_{h_n} g(x)}{h_1 \cdots h_n}$$

holds, which, together with the previous equality implies (22).

The function f is $\bar{\omega}$ -Wright convex if and only if, for all $h_1, \dots, h_n > 0$ and $x \in I \cap (I - (h_1 + \cdots + h_n))$, the left hand side of (22) is nonnegative. According to this equality this happens to be valid if and only if the right hand side is nonnegative, i.e., if f/ω_0 is Wright convex of order $(n-1)$. \square

In the following result, we establish a characterization theorem for $\bar{\omega}$ -Wright convexity provided that the underlying Chebyshev system is strongly related to the polynomial one. This result generalizes the decomposition theorem of Maksa and Páles [7] which is related to the polynomial system. An alternative and more elementary proof of that theorem has been recently given by the authors in [13].

Theorem 3.3. *Assume that there exist a positive continuous function $\omega_0 : I \rightarrow \mathbb{R}_+$ and a matrix $M := (a_{i,j})_{1 \leq i \leq n, 0 \leq j \leq n-1} \in \mathbb{R}^{n \times n}$ such that (14) holds. Define $\omega_{n+1} : I \rightarrow \mathbb{R}$ by $\omega_{n+1}(t) := t^n \omega_0(t)$ and set*

$\bar{\omega} := (\omega, \omega_{n+1})$. Then a function $f : I \rightarrow \mathbb{R}$ is $\bar{\omega}$ -Wright convex if and only if there exist an ω -convex function $F : I \rightarrow \mathbb{R}$ and, for each $k \in \{1, \dots, n - 1\}$, a symmetric k -additive mapping $A_k : \mathbb{R}^k \rightarrow \mathbb{R}$ and a real constant A_0 such that, for all $x \in I$,

$$f(x) = F(x) + (A_0 + A_1(x) + \dots + A_{n-1}(x, \dots, x))\omega_0(x). \tag{24}$$

Proof. To prove the necessity, assume that the function f is $\bar{\omega}$ -Wright convex. Then the assertion (ii) of Theorem 3.2 implies that f/ω_0 is Wright convex of order $(n - 1)$. The decomposition theorem of higher order Wright convex functions [7] implies that there exist a function $G : I \rightarrow \mathbb{R}$ which is convex of order $(n - 1)$, a real constant A_0 and, for each $k \in \{1, \dots, n - 1\}$, a symmetric k -additive mapping $A_k : \mathbb{R}^k \rightarrow \mathbb{R}$ such that, for all $x \in I$,

$$\frac{f}{\omega_0}(x) = G(x) + A_0 + A_1(x) + \dots + A_{n-1}(x, \dots, x). \tag{25}$$

This implies that (24) holds with $F := G\omega_0$ and F/ω_0 is convex of order $(n - 1)$. By assertion (i) of Theorem 3.2, it follows that the function F is ω -convex.

To prove the sufficiency, assume that (24) holds, multiplying (24) by $1/\omega_0(x)$ implies that

$$\frac{f}{\omega_0}(x) = \frac{F}{\omega_0}(x) + (A_0 + A_1(x) + \dots + A_{n-1}(x, \dots, x)).$$

Since the function F is ω -convex, therefore the assertion (i) of Theorem 3.2 implies that F/ω_0 is convex of order $(n - 1)$. Again, by the decomposition theorem of higher order Wright convex functions [7], we can conclude that f/ω_0 is Wright convex of order $(n - 1)$. Thus, the assertion (ii) of Theorem 3.2 yields that the function f is $\bar{\omega}$ -Wright convex. \square

In our subsequent result we will prove that if the extension of the two dimensional polynomial system is not a polynomial of at most second degree, then the convexity with respect to the two dimensional polynomial system (i.e., standard convexity) is equivalent to Wright convexity with respect to this extension. For the proof of this result, we will need the following characterization of a polynomial of at most second degree.

Lemma 3.4. Let $\rho : I \rightarrow \mathbb{R}$ be a continuous function which satisfies the functional equation

$$\frac{\rho(z) - \rho(y)}{z - y} = \frac{\rho(z + u) - \rho(y - u)}{(z + u) - (y - u)}, \quad u \geq 0, y, z \in (I + u) \cap (I - u), z + u \geq y. \tag{26}$$

Then ρ is a polynomial of at most second degree over I .

Proof. If $u > 0$ and $y \in (I + u) \cap (I - u)$, then the limit of the right hand side exists as $z \rightarrow y$ by the continuity of ρ , which shows that ρ is differentiable at y and we get

$$\rho'(y) = \frac{\rho(y + u) - \rho(y - u)}{2u}, \quad u > 0, y \in (I + u) \cap (I - u). \tag{27}$$

Since $u > 0$ was arbitrary, it follows that ρ is differentiable everywhere on I . Now the right hand side of the above equality is differentiable with respect to y , which implies that ρ is twice differentiable. Repeating this argument, it follows that ρ is three times differentiable on I . We are going to show that ρ''' is identically zero on I .

Let $y \in I$ be fixed arbitrarily. Rearranging the equation (27), we can obtain that

$$2u\rho'(y) = \rho(y + u) - \rho(y - u), \quad u \in (y - I) \cap (I - y).$$

Differentiating this equality three times with respect to u , we get that

$$0 = \rho'''(y+u) + \rho'''(y-u), \quad u > 0, y \in (I+u) \cap (I-u).$$

With the substitution $u = 0$, we conclude that $\rho'''(y) = 0$. Therefore, ρ''' is identically zero on I . This yields that ρ has to be a polynomial of at most second degree. \square

Theorem 3.5. *Assume that there exist a positive continuous function $\omega_0 : I \rightarrow \mathbb{R}_+$ and a matrix $M := (a_{i,j})_{1 \leq i \leq 2, 0 \leq j \leq 1} \in \mathbb{R}^{2 \times 2}$ such that (14) holds for $n = 2$. Assume that $\omega_3 : I \rightarrow \mathbb{R}$ is a continuous function such that $\bar{\omega} = (\omega_1, \omega_2, \omega_3)$ is an extension of $\omega = (\omega_1, \omega_2)$ and ω_3/ω_0 is not a polynomial of at most second degree. Then every $\bar{\omega}$ -Wright convex function is ω -convex, i.e., $\bar{\omega}$ -Wright convexity is equivalent to ω -convexity.*

Proof. Under the conditions of the theorem, assume that $f : I \rightarrow \mathbb{R}$ is an $\bar{\omega}$ -Wright convex function. That is, the inequality

$$\frac{\Phi_{(\omega,f)}(x, x+h_1, x+h_1+h_2)}{\Phi_{\bar{\omega}}(x, x+h_1, x+h_1+h_2)} + \frac{\Phi_{(\omega,f)}(x, x+h_2, x+h_1+h_2)}{\Phi_{\bar{\omega}}(x, x+h_2, x+h_1+h_2)} \geq 0$$

holds for all $h_1, h_2 > 0$ and $x \in I \cap (I - (h_1 + h_2))$. Using Lemma 2.7, we can see that this inequality is equivalent to

$$\begin{aligned} & \frac{\omega_0(x)\omega_0(x+h_1)\omega_0(x+h_1+h_2) \cdot \det(M) \cdot \Phi_{\pi_2, f/\omega_0}(x, x+h_1, x+h_1+h_2)}{\omega_0(x)\omega_0(x+h_1)\omega_0(x+h_1+h_2) \cdot \det(M) \cdot \Phi_{\pi_2, \omega_3/\omega_0}(x, x+h_1, x+h_1+h_2)} \\ & + \frac{\omega_0(x)\omega_0(x+h_2)\omega_0(x+h_1+h_2) \cdot \det(M) \cdot \Phi_{\pi_2, f/\omega_0}(x, x+h_2, x+h_1+h_2)}{\omega_0(x)\omega_0(x+h_2)\omega_0(x+h_1+h_2) \cdot \det(M) \cdot \Phi_{\pi_2, \omega_3/\omega_0}(x, x+h_2, x+h_1+h_2)} \geq 0, \end{aligned}$$

which simplifies to

$$\frac{\Phi_{\pi_2, f/\omega_0}(x, x+h_1, x+h_1+h_2)}{\Phi_{\pi_2, \omega_3/\omega_0}(x, x+h_1, x+h_1+h_2)} + \frac{\Phi_{\pi_2, f/\omega_0}(x, x+h_2, x+h_1+h_2)}{\Phi_{\pi_2, \omega_3/\omega_0}(x, x+h_2, x+h_1+h_2)} \geq 0. \quad (28)$$

This means that $g := f/\omega_0$ is $\bar{\pi}_2$ -Wright convex, where $\bar{\pi}_2(t) := (1, t, \rho(t))$ and $\rho := \omega_3/\omega_0$. Observe that, for $\varphi \in \{g, \rho\}$ and $i \in \{1, 2\}$, we have

$$\begin{aligned} \Phi_{(\pi_2, \varphi)}(x, x+h_i, x+h_1+h_2) &= \begin{vmatrix} 1 & 1 & 1 \\ x & x+h_i & x+h_1+h_2 \\ \varphi(x) & \varphi(x+h_i) & \varphi(x+h_1+h_2) \end{vmatrix} \\ &= h_{3-i}\varphi(x) - (h_1+h_2)\varphi(x+h_i) + h_i\varphi(x+h_1+h_2). \end{aligned}$$

Using this formula, the inequality (28) now states that

$$\begin{aligned} & \frac{h_2g(x) - (h_1+h_2)g(x+h_1) + h_1g(x+h_1+h_2)}{h_2\rho(x) - (h_1+h_2)\rho(x+h_1) + h_1\rho(x+h_1+h_2)} \\ & + \frac{h_1g(x) - (h_1+h_2)g(x+h_2) + h_2g(x+h_1+h_2)}{h_1\rho(x) - (h_1+h_2)\rho(x+h_2) + h_2\rho(x+h_1+h_2)} \geq 0 \end{aligned} \quad (29)$$

holds for all $h_1, h_2 > 0$ and $x \in I \cap (I - (h_1 + h_2))$.

By our assumptions, (π_2, ρ) is an extension of π_2 and ρ is not a polynomial of at most second degree. Using Lemma 3.4, it follows that ρ cannot satisfy the functional equation (26), which means that there exist $u \geq 0, y, z \in (I+u) \cap (I-u)$ with $z+u \geq y$ such that

$$\frac{\rho(z) - \rho(y)}{z - y} \neq \frac{\rho(z + u) - \rho(y - u)}{(z + u) - (y - u)}.$$

Let $x := y - u$, $h := z - y + 2u$, $t := z - y + u$. Then $z = x + t$, $y = x + h - t$ and $z + u = x + h$, therefore the above relations state that

$$h(\rho(x + t) - \rho(x + h - t)) + (h - 2t)(\rho(x + h) - \rho(x)) \neq 0 \tag{30}$$

for some $h > 0$, $x \in I \cap (I - h)$ and $t \in (0, h)$.

Let $h > 0$ and $x \in I \cap (I - h)$ be fixed such that, for some $t \in (0, h)$, (30) holds. Define $T \subseteq (0, h)$ to be the set of those values t for which (30) is valid. Then the set T is nonempty and, by the continuity of ρ , it is also open. Let T_+ and T_- denote the (disjoint) subsets of those elements $t \in T$, for which the left hand side of (30) is positive and negative, respectively. Then at least one of these subsets is nonempty (and also open).

Since g is $\bar{\pi}_2$ -Wright convex, hence Theorem 3.1 implies that g is π_2 -Jensen convex, i.e., it is Jensen convex in the standard sense. According to Rodé’s Theorem [15], g is the pointwise maximum of Jensen affine functions, i.e., for all $p \in I$, there exists an additive function $A_p : \mathbb{R} \rightarrow \mathbb{R}$ such that

$$g(y) \geq A_p(y - p) + g(p) \quad (p, y \in I). \tag{31}$$

Substituting $y := x + t$ and $y := x + h - t$, for $t \in T$ and $p \in I$, we get

$$g(x + t) \geq A_p(x + t - p) + g(p), \quad g(x + h - t) \geq A_p(x + h - t - p) + g(p).$$

Therefore, with $h_1 := t$ and $h_2 := h - t$, the inequality (29) yields that

$$\begin{aligned} & \frac{(h - t)g(x) - h(A_p(x + t - p) + g(p)) + tg(x + h)}{(h - t)\rho(x) - h\rho(x + t) + t\rho(x + h)} \\ & + \frac{tg(x) - h(A_p(x + h - t - p) + g(p)) + (h - t)g(x + h)}{t\rho(x) - h\rho(x + h - t) + (h - t)\rho(x + h)} \geq 0. \end{aligned}$$

Using the additivity of A_p and moving the terms containing $A_p(t)$ to the right hand side, this inequality is equivalent to

$$\begin{aligned} & \frac{(h - t)g(x) - h(A_p(x - p) + g(p)) + tg(x + h)}{(h - t)\rho(x) - h\rho(x + t) + t\rho(x + h)} \\ & + \frac{tg(x) - h(A_p(x + h - p) + g(p)) + (h - t)g(x + h)}{t\rho(x) - h\rho(x + h - t) + (h - t)\rho(x + h)} \tag{32} \\ & \geq \frac{h(\rho(x + t) - \rho(x + h - t)) + (h - 2t)(\rho(x + h) - \rho(x))}{((h - t)\rho(x) - h\rho(x + t) + t\rho(x + h))(t\rho(x) - h\rho(x + h - t) + (h - t)\rho(x + h))} hA_p(t). \end{aligned}$$

This inequality shows that A_p is bounded from above on T_+ and is bounded from below on T_- . Therefore, A_p is bounded from above or from below on a nonempty open subset of T . In view well-known properties of additive functions, this implies that A_p is continuous, i.e., there exists a real constant a_p such that $A_p(x) = a_p x$ holds for all $x \in \mathbb{R}$. Thus, by (31), we can see that g is the pointwise maximum of continuous affine functions. Therefore, g must be a convex function (in the standard sense). From this it follows that $f = g\omega_0$ is ω -convex. \square

It seems to be an open problem whether an analogue of the previous theorem is valid for the 3- or higher-dimensional setting.

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