

## **FUZZY LOGIC-BASED MAINTENANCE DECISION**

The real world has some uncertainty and people do not always use precise definitions. The very great experience of engineers and technicians is similar to the real world's feature mentioned above. The fuzzy logic based methods can be used to make maintenance management-decision. This paper shows an example to determine time between state-estimation and permissible parameter values.

### **INTRODUCTION**

As humans, we often rely on imprecise expressions like “usually”, “expensive” or “far”. Therefore, the real world has some uncertainty and people do not use always-precise definitions. In the engineering these ones can be error in measurement, inaccuracy results from digitalization or the integrated system's parameter-uncertainties.

The fuzzy logic is a relatively new mathematical tool, which can be used to model the inaccuracies and uncertainties of the real world mentioned above. LOFTI ZADEH, at the BERKELEY UNIVERSITY, issued first publications in the middle of 60's about the fuzzy logic. He was the first researcher who successfully applied non-binary logic in his work and called this part of the mathematics as “fuzzy”. Within conventional logic, terms can be only “true” or “false”. Fuzzy logic allows a generalization of conventional logic. It provides for terms between “true” and “false” like “almost true” or “partially false” [1].

In the aircraft engineering and in the technical management, the fuzzy logic is – can be or should be – used as a fuzzy control, decision making and diagnostic expert systems.

The very great experience of engineers and technicians is similar to the real world's characteristics mentioned above. This experience can be analyzed and utilized statistically applying the fuzzy logic. The fuzzy logic based methods can be used during trouble-shooting and to make management-decision. Using the fuzzy logic, the experts can model and solve the complicated and antinomic tasks.

The author met similar problem his earlier scientific work, when he developed a mathematical model-based maintenance management method [7]. The regulations and technical specifications do not have date about the permissible parameter values of pneumatic break system of helicopter Mi-8. Therefore the experts (pilots and

mechanical engineers) were reported. The Table 1. shows statistical results of survey. The valuable answerers were 35% of the expert population.

Statistical Results of Expert Reports Table 1.

Permissible values		Engineers	Pilots
Break-effort [%]	Minimum	0,0	0,0
	Maximum	50,0	50,0
	Medium	20,5	17,8
	Median	20,0	17,5
Break asymmetry [%]	Minimum	0,0	0,0
	Maximum	35,0	25,0
	Medium	10,1	7,4
	Median	5,0	5,0
Correlation between parameters		0,475	0,164
Times between state-estimations			
Flying hours [hour]	Minimum	5,0	
	Maximum	200,0	
	Medium	79,8	
	Median	100,0	
Calendar time [day]	Minimum	3,0	
	Maximum	365	
	Medium	120,7	
	Median	60	

## DETERMINATION OF PERMISSIBLE PARAMETERS

To determine the permissible parameters on depend of expert reports the logical expression of decision should be taken down:

$$\begin{array}{l}
 \mathbf{IF} \quad \text{break-effort} \\
 \mathbf{OR} \quad \text{break asymmetry meets the critical value} \\
 \mathbf{THEN} \quad \text{the system should be maintained.}
 \end{array} \quad (1)$$

The membership functions of necessity of break-effort and break asymmetry determined by Table 1. are shown by Fig 1.

It is interesting to mention that pilots suggested lesser permissible parameters than

engineers did. Because of they experience consequence of failure directly. But engineers have stronger correlation between break-effort and asymmetry. These can be expounded that engineers have more consequent technical knowledge. The main task and aim of fuzzy logic is to model and solve mathematically these different opinions. Analog fuzzy one of logical operation **OR** is the **MAXIMUM**, so the logical expression (1) meets the given value if one of assumptions meets it. Therefore the determination of permissible values is to determine parameter values, in case of which their truth-values meet the given value.

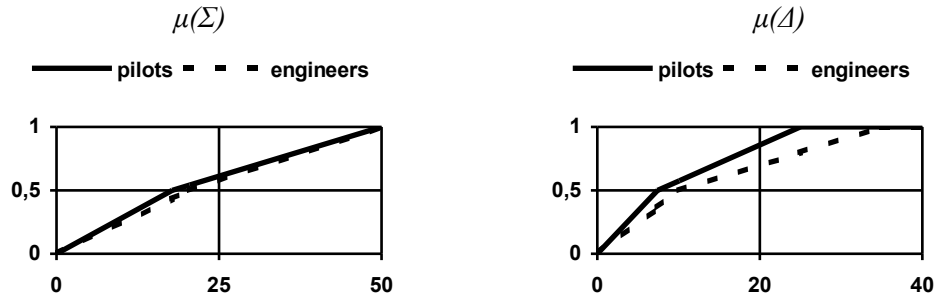


Fig. 1. Membership Functions of Permissible Values

It is expedient that the permissible truth-value of logical expression (1) is 0,7 ~ 0,8. It means that the truth-value of inadmissibility of maintenance of break-system is 0,3 ~ 0,2.

Permissible Values Determined by Fuzzy logic Table 2.

	$\delta F_{\Sigma h} [\%]$		$\delta F_{\Delta h} [\%]$	
	$\mu(\Sigma) = 0,7$	$\mu(\Sigma) = 0,8$	$\mu(\Delta) = 0,7$	$\mu(\Delta) = 0,8$
Pilots	30,68	37,10	14,44	17,96
Engineers	32,30	38,20	20,06	25,04

The Table 2. shows permissible values of parameters incident to the truth-values mentioned above.

## DETERMINATION OF TIME BETWEEN STATE-ESTIMATIONS

Because of the developed diagnostic method should be adapted to an existing maintenance system, the state-estimation can be applied in earlier-determined period.

To determine time between state-estimations firstly the logical expression of decision should be taken down:

$$\begin{array}{ll}
 \text{IF} & \text{checking is need taking into calendar time} \\
 \text{OR} & \text{taking into flying hours} \\
 \text{THEN} & \text{state-estimation is need.}
 \end{array} \quad (2)$$

The membership functions of necessity depend on calendar and flying time determined by Table 1. can be seen in Fig. 2. These functions have been determined by results of the expert reports mentioned above.

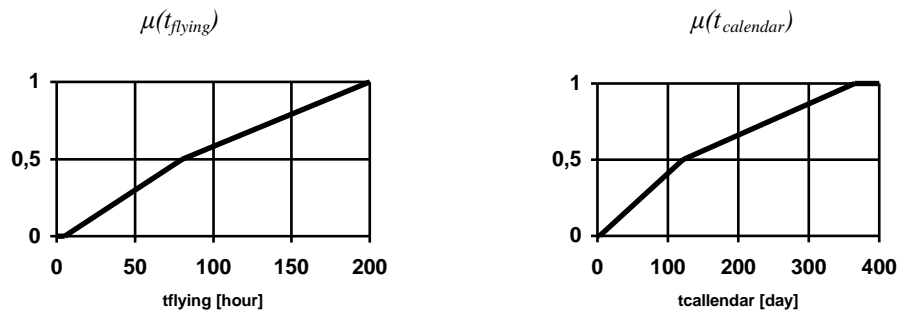


Fig. 2. Membership Function of Times

The task is to determine truth-values of expression (2) in case of practicable (used) calendar and flying time periods (see Table 3.).

Truth-values of Practicable Time Periods Table 3.

by Flying Time	$t_{flying}$ [hour]	$\mu(t_{flying})$	by Calendar Time	$t_{calendar}$ [nap]	$\mu(t_{calendar})$
$50^{+10}$ hour	60	0,367	After $60^{+5}$ days	65	0,263
	45	0,267		60	0,242
$100^{+20}$ hour	120	0,667	During provisions	240	0,745
	90	0,542		120	0,496
$200^{+40}$ hour	240	1			
	180	0,917			

The recommended truth-value of logical expression (2), that is necessity of system controlling is 0,7 ~ 0,8. This means that needless of state-estimation is 0,2 ~ 0,3.

Therefore, the suggested times between state-estimation of pneumatic break system of helicopter Mi-8 *Hip* are:

$$100^{+20-10} \text{ flying hours}$$

and

during summer and winter provisions.

It is important to mention that these results are less weighty than ones determined by other (statistical) methods. The time intervals are longer and permissible parameter values were augmented too. The author thinks that the results of fuzzy investigation mentioned above are fitter than other ones. But he cannot explain his opinion exactly, “only” on the basis of his experiences got during longtime practical and mathematical modeling work.

## CLOSING REMARKS

This paper showed the possibilities of use of fuzzy logic during maintenance decision making. This methods was shown by simplified determination of permissible parameter values and inter-state-estimation times of pneumatic break system of helicopter Mi-8 *Hip*.

## REFERENCES

- [1] BORGULYA, I.: Neurális hálók és fuzzy-rendszerek, Dialóg Campus, Budapest–Pécs, 1998, pp226.
- [2] BOWLES, J. B., PELÁEZ, C. E., Fuzzy Logic Prioritization of Faliures in a System Failure Mode, Effect and Criticality Analysis, Reliability Engineering and System Safety 50 (1995) p. 203-213.
- [3] DANILOV, V.A.: Vertolet Mi-8, Transport, Moscow, 1988.
- [4] GIRARDELLI, E., DIDÓ, F.: Diagnostic from System Models: The Adam System Approach, Proceedings of the 21<sup>st</sup> ICAS Congress, Melbourne, 1998 (CD version).
- [5] POKORÁDI L.: Fuzzy Logic — The Mathematical Base of Robot Technique, Robot Warfare, Porceedings of Conference on Robot Warfare, Budapest, 2001, p. 83-92.,
- [6] <http://www.zmne.hu/tanszekek/ehc/konferencia/april2001/pokoradi.html>.
- [7] POKORÁDI L.: Fuzzy Technique in the Aircraft Engineering, Proceedings of VSDIA 2000, Budapest (under publishing).
- [8] POKORÁDI, L., SZABOLCSI, R.: Aircraft Operation Management Based on State-Estimation, Proceedings of 21<sup>st</sup> ICAS Congress, 13-18 September 1998, Melbourne, Victoria, Australia (CD-version).
- [9] ROHÁCS, J., POKORÁDI, L., ÓVÁRI, GY., KAVAS, L.: Anomalies in Integrated Aircraft Systems, Proceedings of the AIMS 2000, Garmish-Partenkirchen, 2000, p. 269-281.
- [10] XIZHAO W., BIN CH., GUOLIANG Q., FENG Y.: On the Optimization of Fuzzy Decision Trees, Fuzzy Sets and Systems 112 (2000), p. 117-125.

## ACKNOWLEDGEMENT

This work has been supported by Széchenyi Professorship through grant No SzPÖ 0042/99, which is gratefully acknowledged.