

## APPLICATION OF LIDAR TECHNOLOGY IN CATTLE GRAZING AREAS

Tamás János\*, Kiss Nikolett Éva\*, Riczu Péter\*, Gálya Bernadett\*, Budayné-Bódi Erika\*,  
Gross Miklós\*\*, Nagy Attila\*

\*University of Debrecen, Faculty of Agricultural and Food Sciences and Environmental  
Management, Institute of Water and Environmental Management, Debrecen, Hungary,

e-mail: [kiss.nikoletteva@agr.unideb.hu](mailto:kiss.nikoletteva@agr.unideb.hu)

\*\*EUROSENSE Ltd., Hungary

### Abstract

*Precision farming technologies increasingly appear in the livestock sector. The most precision animal husbandry innovations are in the precision breeding and nutrition, but nowadays, different robots (e.g. robotic milking systems, robotic barn cleaners, etc.) can help for effective animal production, mainly in barn. The number of such innovative solutions in field is less. In order to collect spatial information about the ethology of animals, grazing dairy cattle are survey by LiDAR sensor. The focus area is a pasture near Nyírbátor (BÁTORTRADE Trade and Services Ltd., North Trans Tisza Region, Hungary). Application of LiDAR terrain characteristic, topography, vegetation status (e.g. the qualitative and quantitative characteristic of vegetation) and grazing cattle in the pasture can be detected. The main goal of our study was to detect grazing cattle on field by ALS system. LiDAR data was useful for animal detection, and based on the spatial data lying and standing animals were identified distinguishing from each other. In order to examine the statically position of cattle, digital elevation model was created based on the high precision spatial data. Based on the distribution and behaviour of the animals, different problems (e.g. environmental stress) in animal husbandry could be concluded. Multispectral image pattern and monitoring the spatial distribution of cattle's movement, wet locations can be identified on the pasture. Using LiDAR data seems a promising opportunity to optimize land use and livestock size.*

**Key words:** LiDAR, ethology, vegetation status, terrain characteristic

### INTRODUCTION

Today, more and more areas require accurate, reliable and up-to-date characterization of Earth's surface and terrain. The currently rarely applied, but emerging airborne laser scanner (ALS, Airborne Laser Scanning, also known as LiDAR, Light Detection and Ranging) satisfies these needs with the speed of data extraction, the amount and accuracy of the information to be extracted. The LiDAR is an active remote sensing system with his own signal destination (Mutlu et al., 2008; Székely et al., 2007). It is similar to a sonar which uses sound waves or a radar which uses radio waves to map things. But a LiDAR system based on light-emitting and detection, which uses light sent out from a laser to measure the elevations of things, for example ground, forests or buildings. This remote sensing method is measure the distance between the emitting device and the reflecting surface with a laser light (Drosos and Farmakis, 2006; Liu, 2008; Lloyd and Atkinson, 2005).

---

# Corresponding author

There are three different ways to collect LiDAR data: from the ground, from the airplane and even from the space. From these the most commonly applied data is the airborne LiDAR data, when a laser scanner – which attached to an airplane or helicopter, or drone (Neonic, 2014) – creates 3D point cloud model of the surface.

The emitted laser light reflects from the objects on the surface and the system records the time between transmitted and backscattered pulses. Since the speed of light is known the distance can be calculated (Csiha et al., 2017; Doneus et al., 2015; Drosos and Farmakis, 2006; Liu, 2008; Lloyd and Atkinson, 2005; Riczu et al., 2016). To image objects it uses ultraviolet, visible or near infrared light (Cracknell and Hayes, 2007).

The airborne laser scanning can be used in, such as forestry, including forest fire management (Fernandes et al., 2004; Lohr, 1998; Mutlu et al., 2008; Saye et al., 2005; Tamás et al., 2011; Tamás et al., 2013; Utkin et al., 2002), coastal surveys (Lohr, 1998; Saye et al., 2005), geomorphological research (Eeckhaut et al., 2007; Kasai et al., 2009), archaeological surveys (Bewley et al., 2005; Challis, 2006; Devereux et al., 2008) and infrastructural and environmental projects (Challis et al., 2008; Wehr and Lohr, 1999).

The reasons of this wide application area of this technology are the speed of surveying, relatively large surveyed area and acquiring of high resolution data.

In agriculture, for example in grazing, the application of remote sensing instruments provides an opportunity to examine the heterogeneity of the vegetation in the pasture (Tamás et al., 2014) and study the animal behaviour. In this study besides the terrain characteristic, vegetation status and topography, we also detected the grazing cattle on the pasture. The advantage of LiDAR as a remote sensing technology is that it doesn't have to be in direct contact with the tested object, so it doesn't disturb the natural behaviour of animals.

## **MATERIAL AND METHOD**

The sample area was located near to Nyírbátor, easter part of Hungary (Fig. 1), which is owned by the Bátortrade Corporation and the grazing area was part of the LiDAR survey.

The laser surveys were carried out by Eurosense Ltd. in Feburary, 2017. The laser measurement was performed using the IGI LiteMapper system. The LM 6800 can perform up to 400.000 points per second (laser PRR: 400 kHz). The scanner and related processing software (RiAnALYZE 6.0.2, RiWORLD 4.3.7, TerraScan v16, TerraMatch) can also use waveform analysis.

The high-resolution survey covered 107.8 ha, which contains the arable and the grassland also. The area was built from 129.072.937 points. The resolution of the LiDAR data points is 14.58 points/m<sup>2</sup>, which is appropriate for high resolution models.

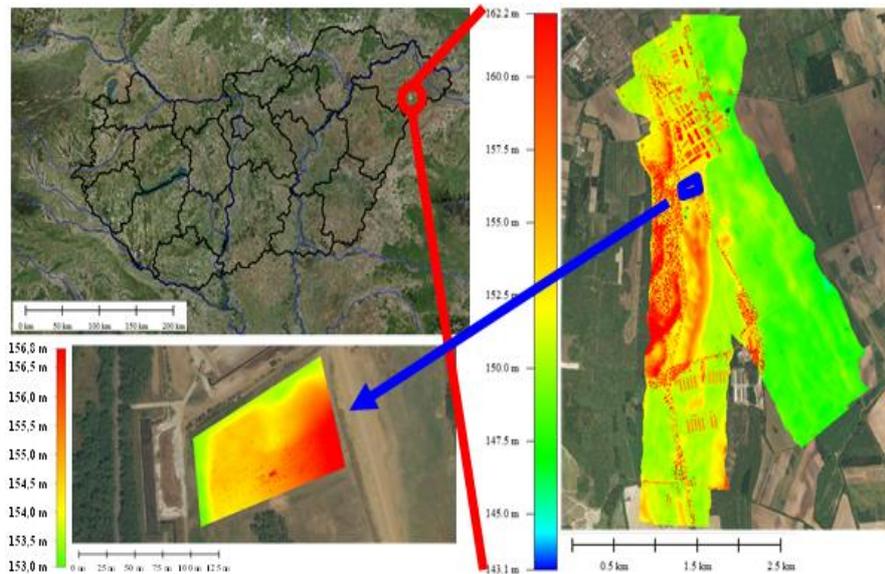


Fig. 1. The surveyed area in Nyírbátor

In this research, our evaluation was carried out in a small part of the grassland, which was 4.7 ha (and it contains more than 2.5 million points, 33.08 points/m<sup>2</sup>). The airborne laser data allows the unique identification and monitoring of the cattle, so not only the status of the pasture were measured, but we also get information about the grazing cattle's ethology, the behaviour of animals. The processing of the data was made in ENVI LiDAR software environment.

As the figure 2 shows the Digital Surface Model (DSM) displays the land surface with all the objects (both natural and artificial also) on the area. The DSM shows where and how much vegetation is growing, so it is useful for the vegetation management. In other application areas the DSM is also useful for view obstruction and runway approach zone encroachment.

If we void the artificial (power lines, buildings and towers) and natural (trees, other types of vegetation) objects, we generate a Digital Elevation Model (DEM). The DEM is useful in soil mapping, hydrologic modelling, terrain stability and land use planning (GIS Geography, 2017). In contrast, in the DSM, all object covered by a mesh.

## RESULTS AND DISCUSSION

The results of the surveying method are called point cloud, which is a set of data in a 3D coordinate system and these data represent the external surface of an object (Axelsson, 1999; Drosos and Farmakis, 2006). Laser data provides an opportunity to segment different surfaces, such a grazing animals or canopy coverage. In this case, the lying and standing animals were distinguished, since this method is suitable for segment the grazing and/or digesting cattle.

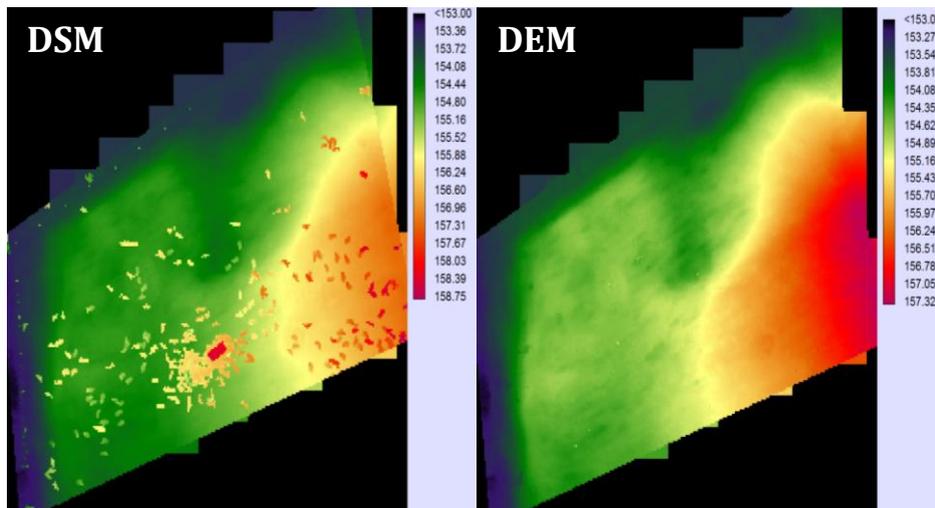


Fig. 2. The DSM and DEM of the grazing area

Objects above ground can be visualized by subtract DEM from DSM. That way watering facilities and other noise effects were separated from the animals.

Figure 3 shows the alignment of animals at the moment of the survey, where the animals group around the feeding place. Based on the pixels of cows, a height histogram was created as it shown in the figure 3. By this elevation histogram the standing and lying cows can be separated from each other. The separation threshold was on 1 m, so above 1 m, animals are standing, below 1 m, animals are lying.

By frequency of pixels, the average area of a cow can be calculated ( $2.54 \text{ m}^2$ ). According to our calculations the total area of standing cows is  $406.25 \text{ m}^2$  and  $278.25 \text{ m}^2$  the area of lying cows, which means that about 160 cows stands and 110 lies.

This surveying just was a one-time occasion, but with multiple LiDAR surveys the movement of livestock and the alignment of the animals

could be monitored. A surveying method would be important before and during the grazing.

Previous to precision cattle grazing it is required to know the area, because the pasture should fulfil the feeding requirements of the animal. By analysis of multispectral images qualitative and quantitative characteristics of the vegetation (biodiversity, invasive plants etc.) can be concluded. The surveying also would be important during the grazing, because the grazing cattle modifies its environment. In other researches, this method could be extended to monitoring other animal species, for example it would also be possible to observe the wild population on different regions.

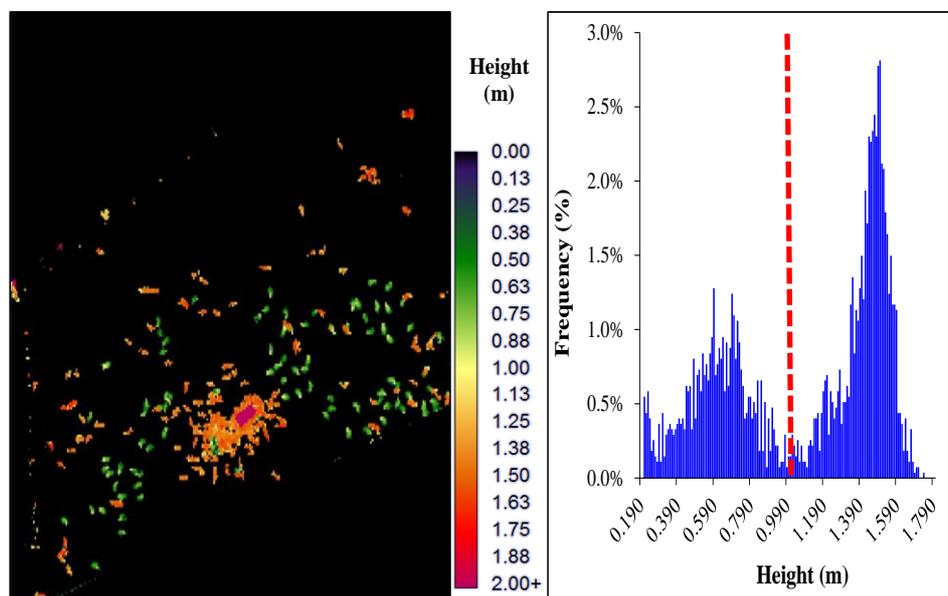


Fig. 3. Frequency of standing and lying animals

## CONCLUSIONS

Summary the application of remote sensing technology in animal husbandry provides an opportunity to observe animal behavior and its changes, and also suitable to examine the welfare of cattle. By remote sensing the information about the temporal and spatial changes of the pasture (e.g. soil, vegetation, grazing ability etc.) also provided.

## Acknowledgment

The research was financed by the Higher Education Institutional Excellence Programme (20428-3/2018/FEKUTSTRAT) of the Ministry of Human Capacities in Hungary, within the framework of the 4. thematic programme of the University of Debrecen.

## REFERENCES

1. Axelsson P., 1999, Processing of laser scanner data – algorithms and applications. *ISPRS Journal of Photogrammetry and Remote Sensing*, 54, pp.138-147;
2. Bewley R.H., Crutchley S.R., Shell C.A., 2005, New light on an ancient landscape; lidar survey in the Stonehenge World Heritage Site. *Antiquity*, 79, pp.636-647;
3. Challis K., 2006, Airborne laser altimetry in alluviated landscapes. *Archaeological Prospection*, 13, pp.103-127;
4. Challis K., Kokalj Z., Kinsey M., Moscrop D., Howard A.J., 2008, Airborne lidar and historic environment. *Antiquity*, 82, pp.1055-1064;
5. Cracknell A.P., Hayes L., 2007, *Introduction to Remote Sensing* (2 ed.). Taylor and Francis, London;
6. Csiha I., Gálya B., Kovács Cs., Riczu P., Tamás J., 2017, Evaluation of site using LiDAR technology pp.657-664. 8 p. In: Blokhina, S Yu; Ageenkova, O A; Tsvilev, A Yu (ed.) *Proceedings of the International Conference devoted to the 85th Anniversary of the Agrophysical Research Institute - Agrophysical Trends: from Actual Challenges in Arable Farming and Crop Growing Towards Advanced Technologies: Tendencii razvitiâ agrifiziki: ot aktual'nyh problem zemledeliâ i rastenievodstva k tehnologiâm budușego*, Sankt-Peterburg, Oroszország: Agrophysical Research Institute;
7. Devereux B., Amable G., Crow P., 2008, Visualization of LiDAR terrain models for archaeological feature detection. *Antiquity*, 82, pp.470-479;
8. Doneus M., Miholjek I., Mandlbürger G., Doneus N., Verhoeven G., Briese Ch., Pregesbauer M., 2015, Airborne laser bathymetry for documentation of submerged archaeological sites in shallow water. *ISPRS – International Archives of the Photogrammetry, Remote Sensing and Spatial Information Sciences, Volume XL-5/W5, Underwater 3D Recording and Modeling*, 16-17 April 2015, Piano di Sorrento, Italy, pp.99-107;
9. Drosos V., Farmakis D., 2006, Airborne laser scanning and DTM generation. In: Manolas, E. (eds.): *Naxos International conference on sustainable management and development of mountains and island areas*, Greece, pp.206-218;
10. Eeckhaut M.V.D., Verstraeten G., Poesen J., 2007, Morphology and internal structure of a dormant landslide in a hilly area: The Collinabos landslide (Belgium). *Geomorphology*, 89, pp.258-273;
11. Fernandes A.M., Utkin A.B., Lavrov A.V., Vilar R.M., 2004, Development of neural network committee machines for automatic forest detection using lidar. *Pattern Recognition*, 37, pp.2039-2047;
12. GIS Geography, 2017, DEM, DSM & DTM Differences – A Look at Elevation Models in GIS. [Online] <http://gisgeography.com/dem-dsm-dtm-differences/>;
13. Kasai M., Ikeda M., Asahina T., Fujisawa K., 2009, LiDAR-derived DEM evaluation of deep-seated landslides in a steep and rocky region of Japan. *Geomorphology*, 113, pp.57-69;
14. Liu X., 2008, Airborne LiDAR for DEM generation: Some critical issues. *Physical Geography*, 32, pp.31-49;
15. Lloyd C.D., Atkinson P.M., 2005, Deriving ground surface digital elevation models from LiDAR data with geostatistics. *International Journal of Geographical Information Science*, 20, pp.535-563;
16. Lohr U., 1998, Digital elevation model by laser scanning. *Photogrammetric Record*, 16, pp.105-109;

17. Mutlu M., Popescu S.C., Zhao K., 2008, Sensitivity analysis of fire behaviour modelling with LIDAR-derived surface fuel maps. *Forest Ecology and Management*, 256, pp.289-294;
18. Neoninc, 2014, How a Light Detection and Ranging (LiDAR) System works. [Online] 12. 10. 2014.] <http://www.neoninc.org/updates-events/update/how-light-detection-and-ranging-lidar-system-works-%E2%80%93-newest-neon-video>;
19. Riczu P., Gombosné N.I., Tamás J., 2016, Airborne LiDAR point cloud based agricultural and pond culture modeling. In: Sang, M. L. – Jin S. P. WCCA AFITA, pp.1-5;
20. Saye S.E., Wal D.v.d., Pye K., Blott S.J., 2005, Beach-dune morphological relationships and erosion/accretion: An investigation at five sites in England and Wales using LiDAR data. *Geomorphology*, 72, pp.128-155;
21. Székely B., Molnár G., Roncat A., 2007, Digital terrain and surface models by full-waveform laser scanning. *Geodézia és Kartográfia*, 59, pp.8-13;
22. Tamás J., Riczu P., Nagy G., Nagy A., Fórián T., Szöllősi N., Fehér J., Rahner S., Heilmeyer H., Hunyadi G., 2011, Integrated hyperspectral and LIDAR technology to evaluate the condition of the 'Debrecen-hajdúböszörményi tölgyesek' (Debrecen-hajdúböszörményi oak forests) Natura 2000 site. pp. 77-78., 2 p. In: WWF, Hungary; Duna-Ipoly, Nemzeti Park Igazgatóság (szerk.) *Steppe Oak Woods and Pannonic Sand Steppes Conference*, Budapest, Magyarország: Duna-Ipoly Nemzeti Park Igazgatóság, (2011) pp.90;
23. Tamás J., Lehoczky É., Nagy S., Verdó Gy., Riczu P., Nagy A., Fehér J., Baranyi B., 2013, Ecological Service Analysis of the Great Forest in Debrecen by LAS/HS Method. pp.275-290. In: Ede, Lázár; Beáta, Kádár (szerk.) *Economic environment changes in the Carpathian Basin Csíkszereda, Románia: Státus Kiadó*, (2014) pp.314;
24. Tamás J., Lehoczky É., Fehér J., Fórián T., Nagy A., Bozsik É., Gálya B., Riczu P., 2014, Airborne hyperspectral and LiDAR data integration for weed detection Paper: EGU2014-12562-1, 1 p. In: European Geosciences Union, General Assembly Vienna, Ausztria;
25. Utkin A.B., Lavrov A.V., Costa L., Simoes F., Vilar R., 2002, Detection of small forest fires by LiDAR. *Applied Physics*, 74, pp.77-83;
26. Wehr U., Lohr U., 1999, Airborne laser scanning – an introduction and overview. *ISPRS Journal of Photogrammetry and Remote Sensing*, 54, pp.68-82.

Received: November 29, 2018

Revised: October 01, 2019